

# HMC6000A/HMC6000A 2

# DIESEL ENGINE CONTROLLER

# **USER MANUAL**



SMARTGEN (ZHENGZHOU) TECHNOLOGY CO., LTD.



SmartGen<sub>English trademark</sub>

SmartGen – make your generator *smart* 

SMARTGEN(ZHENGZHOU) TECHNOLOGY CO., LTD.

No. 28 Jinsuo Road, Zhengzhou City, Henan Province, P. R. China

**Tel:** +86-371-679888888/67981888/67992951

+86-371-67981000(overseas)

Fax: +86-371-67992952

Web: www.smartgen.com.cn

www.smartgen.cn

Email: sales@smartgen.cn

All rights reserved. No part of this publication may be reproduced in any material form (including photocopying or storing in any medium by electronic means or other) without the written permission of the copyright holder.

Applications for the copyright holder's written permission to reproduce any part of this publication should be addressed to SmartGen Technology at the address above.

Any reference to trademarked product names used within this publication is owned by their respective companies.

SmartGen Technology reserves the right to change the contents of this document without prior notice.

Date	Version	Content	
2016-07-06	1.0	Original release;	
2016- <mark>11-1</mark> 0	1.1	Change input port fixed function to programmable function;	
2017-01-10	1.2	Add output port function-lamp test function;	
2019-02-28	1.3	Add CANBUS Communication.	
2019-05-25	1.4	Fix front foil drawing.	
2020-05-14	1.5	Change module setting contents	
2021-03-21	1.7	Upgrade the translation;	
		Modify the parameter range of "Bat Rated Volt" in Table 8;	
		Change the manual font and the format of header and footer.	

# Table 1 Version History



# CONTENTS

OVERVIEW				
PERFORMANCE AND CHARACTERISTICS	5			
TECHNICAL PARAMETERS	6			
CONTROLLER INFORMATION DISPLAY	7			
OPERATION	8			
<ul> <li>5.1 PUSHBUTTON DESCRIPTION</li> <li>5.2 CONTROLLER PANEL</li> <li>5.3 START/STOP OPERATION OF REMOTE CONTROL</li></ul>	9 9 9			
5.3.3 REMOTE STOP SEQUENCE				
5.5.1 ILLUSTRATION				
5.5.2 LOCAL START SEQUENCE				
ALARMS	13			
6.1 WARNING ALARM				
PARAMETER CONFIGURATION LIST	19			
INPUT/OUTPUT PORT CONFIGURATION	25			
<ul> <li>8.1.1 DIGITAL INPUT PORT CONFIGURATION</li> <li>8.1.2 INPUT PORT FUNCTIONS</li> <li>8.2 OUTPUT PORT DEFINITION</li> </ul>	25 25 26			
8.2.2 OUTPUT PORT 1-12 FUNCTIONS DEFINITION				
8.3 SENSOR FUNCTIONAL CONFIGURATION				
TT.T R5403 AND LINK COMINICATION	ა/			
	PERFORMANCE AND CHARACTERISTICS. TECHNICAL PARAMETERS. CONTROLLER INFORMATION DISPLAY. OPERATION. 5.1 PUSHBUTTON DESCRIPTION. 5.2 CONTROLLER PANEL 5.3 START/STOP OPERATION OF REMOTE CONTROL. 5.3.1 ILLUSTRATION. 5.3.2 REMOTE START SEQUENCE. 5.3.3 REMOTE STOP SEQUENCE. 5.4 AUTO MODE START/STOP OPERATION. 5.4.1 ILLUSTRATION. 5.4.2 AUTO START SEQUENCE. 5.4.3 AUTO STOP SEPUENCE. 5.5.1 ILLUSTRATION. 5.5.1 ILLUSTRATION. 5.5.2 LOCAL START/STOP OPERATION. 5.5.2 LOCAL START SEQUENCE. 5.5.3 LOCAL START SEQUENCE. 5.5.3 LOCAL STOP SEQUENCE. 6.1 WARNING ALARM. 6.2 SHUTDOWN ALARM. PARAMETER CONFIGURATION LIST. INPUT/OUTPUT PORT CONFIGURATION. 8.1 AUXILIARY INPUT 1~10 FUNCTIONAL CONFIGURATION. 8.1.1 DIGITAL INPUT PORT CONFIGURATION. 8.2.0 OUTPUT PORT 1-12 FUNCTIONS DEFINITION. 8.2.1 DIGITAL OUTPUT DEFINITION CONTENTS. 8.2.2 OUTPUT PORT 1-12 FUNCTIONS DEFINITION.			



11.2 CANBUS (EXPANSION) BUS COMMUNICATION	37
11.3 CONTROLLER AND ENGINES CONNECTION (EXPANSION CANBUS)	38
11.3.1 CUMMINS ISB/ISBE	
11.3.2 CUMMINS QSL9	38
11.3.3 CUMMINS QSM11	39
11.3.4 DETROIT DIESEL DDEC III / IV	39
11.3.5 DEUTZ EMR2	39
11.3.6 JOHN DEERE	40
11.3.7 MTU MDEC	40
11.3.8 PERKINS	40
11.3.9 SCANIA	41
11.3.10 VOLVO EDC3	41
11.3.11 VOLVO EDC4	41
11.3.12 VOLVO-EMS2	42
11.3.13 BOSCH	42
11.3.14 POWER WIRING CONNECTION	42
12 HMC6000A 2 APPLICATION DIAGRAM	43
13 COMMISSIONING	
14 INSTALLATION	44
14.1 FIXING CLIPS	44
14.2 OVERALL DIMENSIONS AND CUTOUT DIMENSIONS.	
15 INSTALLATION CAUTIONS	
15.1 BATTERY VOLTAGE INPUT	45
15.2 SPEED SENSOR INPUT	45
15.3 OUTPUT AND EXPANSION RELAY	
15.4 SENSOR INPUT	
16 TROBLESHOOTING	47



#### 1 OVERVIEW

<u>HMC6000A/HMC6000A 2</u> diesel engine controller integrates digitization, intelligentization and network technology which are used for genset automation and monitor control system of single unit to achieve automatic start/stop, data measure, alarm protection and "three remote" (remote control, remote measuring and remote communication). It fit with 132\*64 liquid display, optional Chinese/English languages interface, and it is reliable and easy to use.

The powerful 32-bit ARM processor contained within the module allows for precision parameters measuring, fixed value adjustment, time setting and set value adjusting and etc..Majority parameters can be configured from front panel and can be configured by communication interface via PC. Due to its compact structure, simple connections and high reliability, **HMC6000A/HMC6000A 2** can be widely used in marine emergency engines, main propulsion engines, main generator engines and pumping engines.

**HMC6000A/HMC6000A 2** diesel engine controller has an expansion CANBUS port that will be connected to a remote control module or expansion digital output module and security module.

#### 2 PERFORMANCE AND CHARACTERISTICS

- 32-bit ARM micro-processor, 132\*64 liquid display, optional Chinese/English interface, push-button operation;
- Connect with remote monitoring module via CANBUS (expand) port to realize remote monitoring and remote start/stop control;
- RPU560A security module can be expanded via CANBUS (expand) port;
- Dozens of engine, which is compatible with J1939 protocol, can be monitored via CANBUS(ECU) port;
- RS485 communication ports enable data communication as well as remote control, remote measurement and remote communication;
- Control and protection: remote/local start and stop diesel engine, alarm protection;
- Override mode, in which only overspeed and manual emergency shutdown can stop the engine;
- Parameter setting: parameters can be modified by users and stored into internal FLASH memory and cannot be lost even in case of power outage;
- Six sensor inputs for pressure, temperature, fuel level or other resistor type sensors; pressure sensor and Flexible sensor1~3 also can be set to (4~20)mA input and (0~5)V input;
- Real-time clock, engine total run-time accumulation, display the total start times;
- Built-in speed detection, which can accurately judge crank disconnect status, rated running and overspeed status.
- 99 event logs can be saved circularly and can be inquired on the spot;



- Digital regulation of all parameters instead of analog regulation using conventional potentiometer - and, therefore, higher reliability and stability;
- Modular design, self-extinguishing ABS plastic enclosure and embedded installation way; small size and compact structure with easy mounting

## **3 TECHNICAL PARAMETERS**

#### **Table 2 Technical Parameters**

Items	Content		
Working Voltage	DC8.0V to DC35.0V, uninterrupted power supply		
Power Consumption	<3W (Standby mode: ≤2W)		
Speed Sensor Voltage	1.0V to 24V (RMS)		
Speed Sensor Frequency	Max 10,000 Hz		
Start Relay Output	16 A Connect to common output port		
Stop Relay Output	16 A Connect to common output port		
Fuel Relay Output	16 A Connect to common output port		
Audio Alarm Output	7 A Connect to common output port		
Common Alarm Output	7 A Connect to common output port		
Flexible Relay Output 1-9	B+ DC supply, 0.5A output current		
Flexible Relay Output 10-12	7 A AC250V voltage fr <mark>ee o</mark> utput		
Case Dimension	197 mm x 152 mm x 4 <mark>7 mm</mark>		
Panel Cutout	186mm x 141mm		
Working Conditions	Temperature: (-25~+70)°C; Humidity: (20~93)%RH		
Storage Conditions	Temperature: (-25~+70)°C		
Protection Level	IP65: when water proof gasket ring inserted between panel and housing.		
Weight	0.70kg		
51			



#### 4 CONTROLLER INFORMATION DISPLAY

# Table 3 Controller Information Display

Screen	Display	Description
After pressing "Enter" for	Return	After selected controller information, press
1s, the controller will	Parameter Setting	"Enter" to enter into controller information
enter into parameter	Controller Information	interface.
setting and information		
selection interface.		
First Screen	Controller Information	This screen will display software version,
	Software Version 1.1	hardware version and controller time.
	Release Date 2018-09-05	Press 🙆 or 🗑 to scroll screen.
	2018.10.15(5)09:30:10	Press 🖤 or 🖤 to scroll screen.
Second Screen	0:SFSHA12345	This screen will display output port status, and
	22222222222	engine status.
	6789101112	Press 🙆 or 🗑 to scroll screen.
	22222	Press 🖤 or 🖤 to scroll screen.
	Standby	
Third Screen	l: E 1 2 3 4 5 6 7 8 9	This screen will display input port status, and
	22222	engine status.
	10	Press Or To scroll screen.
	2	Press 🖤 or 🖤 to scroll screen.
	Standby	



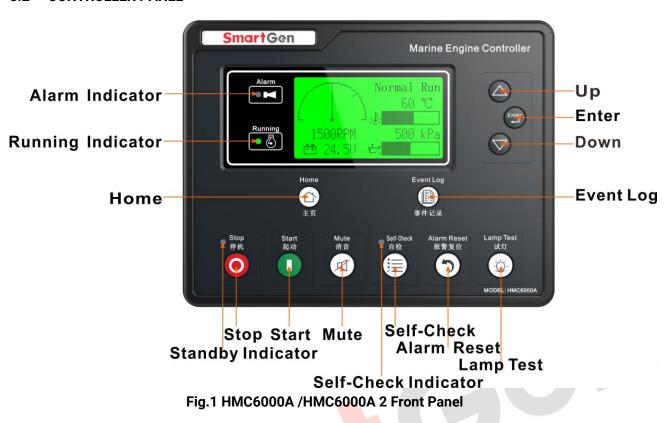
#### **5** OPERATION

#### 5.1 PUSHBUTTON DESCRIPTION

# Table 4 Key Function Description

lcon	Button	Description		
$\bigcirc$	Stop	Stop running generator in local mode; During stopping process, press this button again to stop generator immediately.		
	Start	Start standby genset in local mode.		
	Mute	Alarm sound off.		
	Self-Check	In standby mode, pressing this button, the controller can test alarms in the situation of no rotate speed.		
6	Alarm Reset	If alarm occurs, pressing this button will reset it.		
ĊĊ:	Lamp Test	Press this button will test panel LED indicators and display screen.		
	Home	Shortcut to return to the main screen.		
	Event Log	Shortcut to the alarm history page.		
	Up	<ol> <li>Screen scroll.</li> <li>Up cursor and increase value in setting menu.</li> </ol>		
	Down	<ol> <li>Screen scroll.</li> <li>Down cursor and decrease value in setting menu.</li> </ol>		
Enter	Enter	<ol> <li>Pressing and holding for more than 1 second to entry the parameter configuration and controller info selection menu.</li> <li>In settings menu confirms the set value.</li> </ol>		





#### 5.3 START/STOP OPERATION OF REMOTE CONTROL

#### 5.3.1 ILLUSTRATION

Deploy any digital input port of HMC6000A/HMC6000A 2 to remote start input. After the "remote mode" is active, remote start/stop operation can be initiated.

# 5.3.2 REMOTE START SEQUENCE

- When "Remote Start" input is active, "Start Delay" timer is initiated;
- <u>"Start Delay</u>" countdown will be displayed on LCD;
- After "Start Delay" expired, preheat relay energizes (if configured), "Preheat Delay XX s" information will be displayed on LCD;
- After the above delay, the "Fuel Relay" is energized, and then one second later, the "Start Relay" is engaged. Genset is cranked for a pre-set time. If genset fails to fire during this cranking attempt then the fuel relay and start relay are disengaged for the pre-set rest period; "crank rest time" begins and wait for the next crank attempt;
- Should this start sequence continue beyond the set number of attempts, the start sequence will be terminated, the first line of LCD display will be highlighted with black and Fail to Start fault will be displayed;
- In case of successful crank attempt, the "Safety On" timer is activated. As soon as this delay is over, "start idle" delay is initiated (if configured);
- After the start idle, the generator enters into "Warming Up" status (if configured);
- When "Warming Up" delay is expired, engine will normally run.
  - ▲ **Note:** If engine is started by remote monitoring module, there is no "Start Delay" step, and will jump to "Preheat Delay" directly.



#### 5.3.3 REMOTE STOP SEQUENCE

- When "Stop Input" signal is active, "Stop Delay" timer is initiated;
- After "Stop Delay" expired, cooling will be started;
- After cooling, idle relay is energized while "Stop Idle" (if configured) starts;
- Once this "Stop Idle" has expired, the "ETS Solenoid Hold" begins. ETS relay is energized while fuel relay is de-energized;
- Once this "ETS Solenoid Hold" has expired, the "Wait Stop Time" begins. Complete stop is detected automatically;
- Generator is placed into its standby mode after its complete stop. Otherwise, fail to stop alarm is initiated and the corresponding alarm information is displayed on LCD while entering into "Fail to Stop" status (If generator is stop successfully after "Fail To Stop" alarm has initiated, engine will enter into standby status).
- ▲ **Note:** If engine is stopped by remote monitoring module, there is no "Stop Delay" step, and will jump to cooling step directly.

#### 5.4 AUTO MODE START/STOP OPERATION

#### 5.4.1 ILLUSTRATION

Deploy any digital input port to auto-mode input. After the "Auto Mode" is active, Start/Stop operation can be initiated.

#### 5.4.2 AUTO START SEQUENCE

- When "Auto Start" input is active or "Remote Start/ Stop" input is active, "Preheat Delay" is initiated;
- Preheat relay energizes (if configured), "Preheat Delay XX s" information will be displayed on LCD;
- After the above delay, the "Fuel Relay" is energized, and then one second later, the "Start Relay" is engaged. The genset is cranked for a pre-set time. If the genset fails to fire during this cranking attempt then the fuel relay and start relay are disengaged for the pre-set rest period; "crank rest time" begins and wait for the next crank attempt;
- Should this start sequence continue beyond the set number of attempts, the start sequence will be terminated, the first line of LCD display will be highlighted with black and Fail to Start fault will be displayed;
- In case of successful crank attempt, the "Safety On" timer is activated. As soon as this delay is over, "Start Idle" delay is initiated (if configured);
- When the "Start Idle "delay is over, "Warming Up" delay is initiated (if configured);
- When "Warming Up" delay is over, generator will enter into "Normal Running status".



#### 5.4.3 AUTO STOP SEPUENCE

- When "Stop Input" is active or "Start/Stop" input open, cooling is started;
- Once the "Cooling Delay" has expired, the "Stop Idle" delay is initiated (if configured). During "Stop Idle" Delay, idle relay is energized;
- Once the "Stop Idle" delay has expired, "ETS Solenoid Hold" begins. ETS relay is energized while fuel relay is de-energized;
- Once this "ETS Solenoid Hold" has expired, the "Wait Stop Time" begins. Complete stop is detected automatically;
- Generator is placed into its standby mode after its complete stop. Otherwise, fail to stop alarm is initiated and the corresponding alarm information is displayed on LCD while entering into "Fail to Stop" status (If generator is stop successfully after "Fail To Stop" alarm has initiated, engine will enter into standby status).

#### 5.5 LOCAL START/STOP OPERATION

#### 5.5.1 ILLUSTRATION

Deploy any digital input port to local-mode input. After the "local mode" is active, Start/Stop operation will be doable by pressing buttons on the controller.

Under local-mode, "Idle Output" is unavailable.

#### 5.5.2 LOCAL START SEQUENCE

- Press button to start the gen-set; preheat relay energizes (if configured), "preheat delay XX
   s" information will be displayed on LCD;
- After the above delay, the "Fuel Relay" is energized, and then one second later, the "Start Relay" is engaged. The genset is cranked for a pre-set time. If the genset fails to fire during this cranking attempt then the fuel relay and start relay are disengaged for the pre-set rest period and genset enters into "Energize to Stop" status;
- In case of successful crank attempt, the "Safety On" timer is activated;
- After the "Start Idle" delay expired, if the rotate speed, temperature and oil pressure of controller are regular, the generator will enter into "Normal Running" status directly.

#### 5.5.3 LOCAL STOP SEQUENCE

- Press Obutton to enter into "Energize to Stop" status, ETS relay is energized while fuel relay is de-energized;
- Once the "ETS Solenoid Hold" delay has expired, "Wait Stop Time" begins. Complete stop is detected automatically;
- Generator is placed into its standby mode after its complete stop. Otherwise, fail to stop alarm is



initiated and the corresponding alarm information is displayed on LCD while entering into "Fail to Stop" status (If generator is stop successfully after "Fail To Stop" alarm has initiated, engine will enter into standby status).

System Mode	Local Start	Local Stop	Remote Start Input	Stop Input	Remote Start/Stop Input	Auto Start Input	Remote Module Start	Remote Module Stop
Local	•	•	-	-	-	-	-	-
Remote	-	-	•	•	-	-	٠	•
Auto	-	-	-	•	•	•	-	-

CC

# Table 5 HMC6000A/HMC6000A 2 Start/Stop Description





#### 6 ALARMS

#### 6.1 WARNING ALARM

When controller detects warning alarms, which does not lead to shutdown, the detailed alarm information will be displayed on LCD.

No.	Туре	Detection Range	Description
			When the controller detects that the engine speed has
1			exceeded the pre-set value, it will initiate a warning
1.	Over speed	Always active	alarm and the corresponding alarm information will be
			displayed on LCD.
		From "Morming	When the controller detects that the engine speed has
2.	Under speed	From "Warming	fallen below the pre-set value, it will initiate a warning
Ζ.	under speed	up" to "Cooling" delay	alarm and the corresponding alarm information will be
		delay	displayed on LCD.
		From "Start Idle"	When the controller detects that the engine speed is 0
3.	Loss of Speed	delay to "Stop Idle"	and action select "Warning", it will initiate a warning
5.	Signal	delay	alarm and the corresponding alarm information will be
			displayed on LCD.
			Among set crank times, if genset failed to start, it will
		Among set crank	initiate a warning alarm and the corresponding alarm
4.	Failed to start	times, after "Start	information will be displayed on LCD.
		Completed"	Note: start attempt is forced as 1 time in local mode,
			and no alarms if failed to crank.
		After "Fail to Stop" Delay	After "Fail to Stop" delay, if engine still has speed signal, it
5.	Failed to stop		will initiate a warning alarm and the corresponding alarm
			information will be displayed on LCD.
			When the controller detects that charger voltage has
6.	Charge Alt Fail	When generator is	fallen below the pre-set value, it will initiate a warning
	Charge Alt I all	normal running	alarm and the corresponding alarm information will be
			displayed on LCD.
			When the controller detects that the auxiliary input 1-10
7.	Aux. Input 1-10	User defined	warning signals, it will initiate a warning alarm and the
			corresponding alarm information will be displayed on
			LCD.
			When the controller detects that the high water
8.	High Water Bigger than set		temperature warning signals, it will initiate a warning
	Temperature	speed	alarm and the corresponding alarm information will be
			displayed on LCD.

# **Table 6 Warning Alarms**



No.	Туре	Detection Range	Description
			When the controller detects that the high oil temperature
9.	High Oil	Bigger than set	warning signals, it will initiate a warning alarm and the
	Temperature	speed	corresponding alarm information will be displayed on
			LCD.
			When the controller detects that the low oil pressure
10.	Low Oil Pressure	Bigger than set	warning signals, it will initiate a warning alarm and the
10.	Low OII Pressure	speed	corresponding alarm information will be displayed on
			LCD.
			When the controller detects that the Flexible sensor 1-3
11.	Aux. Sensor 1-3	Bigger than set	warning signals, it will initiate a warning alarm and the
11.	High	speed	corresponding alarm information will be displayed on
			LCD.
			When the controller detects that the Flexible sensor 1-3
12.	Aux. Sensor 1-3	Bigger than set	warning signals, it will initiate a warning alarm and the
12.	Low	speed	corresponding alarm information will be displayed on
			LCD.
	Water Temperature Open	Always active	When the controller detects that the water temperature
13.			senso <mark>r open</mark> warning signals, it will initiate a warning
15.			alarm and the corresponding alarm information will be
			displayed on LCD.
			When the controller detects that the oil temperature
14.	Oil Temperature	Always active	sensor open warning signals, it will initiate a warning
17.	Open	Always active	alarm and the corresponding alarm information will be
			displayed on LCD.
			When the controller detects that the oil pressure sensor
15.	Oil Pressure Open	Always active	open warning signals, it will initiate a warning alarm and
10.			the corresponding alarm information will be displayed
			on LCD.
			When the controller detects that the flexible sensor 1-3
16.	Aux. Sensor 1-3	Always active	open warning signals, it will initiate a warning alarm and
10.	Open	Always active	the corresponding alarm information will be displayed
			on LCD.
			When the controller detects that the supply voltage has
17.	Supply1 Under Volt	Always active	fallen below the pre-set value for more than 20s, it will
			initiate a warning alarm and the corresponding alarm
			information will be displayed on LCD.
18.	Supply 1 Over Volt	Always active	When the controller detects that the supply voltage has
10.			exceeded the pre-set value, it will initiate a warning



No.	Туре	Detection Range	Description
			alarm and the corresponding alarm information will be
			displayed on LCD.
			When the controller detects that the supply voltage has
19.	Supply 2 Under Volt	Always active	fallen below the pre-set value for more than 20s, it will
19.		Always active	initiate a warning alarm and the corresponding alarm
			information will be displayed on LCD.
			When the controller detects that the supply voltage has
20.	Supply 2 Over Volt	Always active	exceeded the pre-set value, it will initiate a warning
20.		Always active	alarm and the corresponding alarm information will be
			displayed on LCD.
		Always active	When the controller detects DOUT 16 module
21.	DOUT 16 Comm.	(When DOUT16 is	communication failure, it will initiate a warning alarm
Ζ1.	Fail	enabled)	and the corresponding alarm information will be
		enabled)	displayed on LCD.
		Always active	When the controller detects HMC6000RM module
22.	HMC6000RM	(When HMC6000RM is enabled)	communication failure, it will initiate a warning alarm
22.	Comm. Fail		and t <mark>he c</mark> orresponding alarm information will be
			displayed on LCD.
		Always active	When the controller detects RPU560A module
23.	RPU560A Comm.	(When RPU560A is	communication failure, it will initiate a warning alarm
20.	Fail	enabled)	and the corresponding alarm information will be
		enabled)	displayed on LCD.
		Always active	When the controller detects HMP300 module
24.	HMP300 Comm.	(When HMP300 is	communication failure, it will initiate a warning alarm
	Fail	enabled)	and the corresponding alarm information will be
			displayed on LCD.
		Always active	When the controller detects HMC9800RM module
25.	HMC9800RM	(When HMC9800	communication failure, it will initiate a warning alarm
20.	Comm. Fail	is enabled)	and the corresponding alarm information will be
			displayed on LCD.(HMC6000A 2 without this item)
	Fresh Water		When the input port defines this function, the controller
26.	Pressure Low Input	Always active	will initiate a warning alarm and the corresponding
			alarm information will be displayed on LCD.
			When the input port defines this function and it is
27.	Fresh Water Level	Always active	active, the controller will initiate a warning alarm and
	Low Input		the corresponding alarm information will be displayed
			on LCD.
28.	Grease Level Low	Always active	When the input port defines this function and it is



No.	Туре	Detection Range	Description
	Input		active, the controller will initiate a warning alarm and
			the corresponding alarm information will be displayed
			on LCD.
			When the input is active, the controller will initiate a
29.	Fuel Leakage Input	Always active.	warning alarm and the corresponding alarm
			information will be displayed on LCD.
	FOLLW :	Always active	When there is ECU warning alarms, the corresponding
30.			alarm information and SPN and FMI will be displayed
	ECU Warning		on LCD. Max.5 SPN codes of ECU alarm can be
			displayed.

**A** Note: The warning types of Auxiliary input are active only when they are configured by users.

▲ Note: The aux. input port 1~10 are corresponding with the input port A~J on the back plate of the controller.

▲ Note: The aux. sensor 1~3 are corresponding with the sensor A~C on the back plate of the controller.

**DOUT16:** 16-channel digital output expansion module.

**RPU560A:** security expansion module.

HMP300: power integrated protection expansion module.

HMC9800RM: remote monitoring expansion module.



#### 6.2 SHUTDOWN ALARM

When controller detects shutdown alarms, controller will stop the genset and corresponding alarm information will display on the LCD.

No.	Туре	Detection Range	Description
1.	Emergency Stop	Always active	When the controller detects that the emergency stop is active, it will initiate a shutdown alarm and the corresponding alarm information will be displayed on LCD.
2.	Over speed	Always active	When the controller detects that the engine speed has exceeded the pre-set value, it will initiate a shutdown alarm and the corresponding alarm information will be displayed on LCD.
3.	Aux. Input 1-10	User defined	When the controller detects that the auxiliary input 1-10 shutdown signals, it will initiate a shutdown alarm and the corresponding alarm information will be displayed on LCD.
4.	High Water Temperature	Bigger than set speed	When the controller detects that the high water temperature shutdown is active, it will initiate a shutdown alarm and the corresponding alarm information will be displayed on LCD.
5.	High Oil Temperature	Bi <mark>gger</mark> than set speed	When the controller detects that the high oil temperature shutdown is active, it will initiate a shutdown alarm and the corresponding alarm information will be displayed on LCD.
6.	Low Oil Pressure	Bigger than set speed	When the controller detects that the low oil pressure shutdown is active, it will initiate a shutdown alarm and the corresponding alarm information will be displayed on LCD.
7.	Aux. Sensor 1-3 High	Bigger than set speed	When the controller detects that the Flexible sensor 1-3 shutdown is active, it will initiate a shutdown alarm and the corresponding alarm information will be displayed on LCD.
8.	Aux. Sensor 1-3 Low	Bigger than set speed	When the controller detects that the Flexible sensor 1-3 shutdown is active, it will initiate a shutdown alarm and the corresponding alarm information will be displayed on LCD.
9.	ECU Shutdown	Always active.	When there is an ECU shutdown alarm, the corresponding alarm information and SPN and FMI will

#### **Table 7 Shutdown Alarms**



No.	Туре	Detection Range	Description	
			be displayed on LCD. Max.5 SPN codes of ECU alarm	
			can be displayed.	
Δ	<b>Note:</b> The shutdown types of Auxiliary input are active only when they are configured by users.			
Δ	<b>Note:</b> The aux. input port $1 \sim 10$ are corresponding with the input port $A \sim J$ on the back plate of the			
cont	controller.			
Δ	<b>Note:</b> The aux. sensor 1~3 are corresponding with the sensor A~C on the back plate of the			
controller.				





## 7 PARAMETER CONFIGURATION LIST

Hold and press for 1s to enter into parameter configuration and controller info selection menu after input the correct password (Default password as 00318). Please contact the manufacturer if forget password or need sensor resistance/current calibration.

Parameter	Range	Default	Remarks
1. Start delay	(1-3600) s	1	The time from remote start signal active to complete start when the controller is in remote mode.
2. Stop delay	(1-3600) s	1	The time from remote stop signal active to complete stop when the controller is in remote mode.
3. Pre-heating delay	(0-3600) s	0	The time of heater plug energized before starter energized.
4. Cranking Time	(3-60) s	8	The every starter energized time.
5. Crank Rest Time	(3-60) s	10	The waiting time before second energizes start when starter failed to start.
6. Safety on Time	(0-3600) s	10	First running time after machine started.
7. Start Idle time	(0-3600) s	0	Idle running time when genset start.
8. Warming Up Time	(0-3600) s	10	Warming up time after genset enters into hi-speed running.
9. Cooling Time	(0-3600)s	10	Cooling time before stop.
10. Stop Idle Time	(0-3600) s	0	Stop idle time when stop.
11. ETS Hold Time	(0-3600) s	20	Stop magnet energized time when the genset is to stop.
12. Wait Stop Time	(0-3600) s	0	Time from idle delay finished to wait stop when "ETS Hold Time" is set to 0; time from ETS hold to wait stop when "ETS Hold Time" isn't set to 0.
13. Start Key Confirm	(0.2-5.0) s	0.2	The time from pressing start button to start performance when the controller starts by button-press.
14. Stop Key Confirm	(0.2-5.0) s	0.2	The time from pressing stop button to stop performance when the controller stops by button-press.
15. J1939 Enable	(0-1) 0: Disabled 1: Enabled	0: Disabled	After enabled, J1939 monitoring can be achieved via select related engine type.
16. Engine Type	(0-39)	0: Conventional Engine	Default: Conventional Genset. When connect to J1939 genset, please select related engine type.
17. SPN Version	(1-3)	1	Alarm analysis type of SPN
18. ECU Shutdown Enable	(0-1)	0: Disabled	After enabled, genset shuts down when detected red lamp alarms.

# Table 8 Parameter Configuration Items



Parameter	Range	Default	Remarks
19. Flywheel teeth	(1-300)	118	The flywheel teeth installed in genset is used for judgment of separate conditions and detection of rotate speed. See 14 Installations.
20. Rated speed	(1-5999)r/min	1500	Provide standard for judgment of over speed and under speed.
21. Start Attempts	(1-30)	3	The maximum of start attempts when genset failed to start. When it arrive pre-set value, the controller will send failed to start signal.
22. Crank Disconnect Condition	(0-2) 0: Speed 1: Oil Press. 2: Speed+ OP	0: Speed	The three disconnection conditions of starter and engine, which can be used alone or simultaneously, are used to make starter motor disconnect with engine as soon as possible.
23. Disconnect OP	(10-1000)kPa	80	Disconnect when Oil Pressure exceeds preset value.
24. Disconnect Speed	(0-200)%	25%	Set value is percentage of rated rotate speed. When speed exceeds pre-set value, starter will separate.
25. Under Speed Shutdown	(0-1) 0 Disabled 1 Enabled	0 Disabled	Under speed shutdown setting.
26. Set Value	(0-200)%	85%	
27. Delay	(0-3600) s	3	
28. Under Speed Warn	(0-1) 0 Disabled 1 Enabled	0 Disabled	
29. Set Value	( <mark>0-20</mark> 0)%	90%	Under speed warning setting.
30. Return Value	(0-200)%	92%	
31. Delay	(0-3600) s	3	
32. Over Speed Shutdown	(0-1) 0 Disabled 1 Enabled	1 Enabled	Over speed shutdown setting.
33. Set Value	(0-200)%	115%	
34. Delay	(0-3600) s	1	
35. Over Speed Warn	(0-1) 0 Disabled 1 Enabled	1 Enabled	Over encod werning estting
36. Set Value	(0-200)%	110%	Over speed warning setting.
37. Return Value	(0-200)%	108%	
38. Delay	(0-3600) s	3	
39. Speed Signal Lose Delay	(0-3600) s	3	The time from that detecting speed is 0 to confirm action.
40. Speed Signal Lose Action	(0-2) 0: Warn	1: Shutdown	The action after detecting loss of speed.



Parameter	Range	Default	Remarks	
	1: Shutdown 2: No Action			
41. Charge Alt Fail	(0-60.0)V	16.0	After engine is normal running, controller will initiate an alarm when voltage of charger falls below this limit.	
42. Bat Rated Volt	(0-60.0)V	24.0	Provide standard for judgment of over voltage and under voltage.	
43. Power 1 Over Volt	(0-200)%	125%	Set value is percentage of power supply	
44. Power 1 Under Volt	(0-200)%	75%	rated voltage.	
45. Power 2 Over Volt	(0-200)%	125%	Set value is percentage of power supply rated voltage.	
46. Power 2 Under Volt	(0-200)%	75%	The main interface won't display voltage of power supply A and B when this value is set as 0. Main interface icon will show battery 1 voltage.	
47. Heating Up Limit	<b>(0-100)</b> ℃	42	Open when temperature of water temperature sensor larger than pre-set value.	
48. Heat Down Limit	<b>(0-100)</b> ℃	37	Close when temperature of water temperature sensor less than pre-set value.	
49. Pre-lubrication Cycle Enable	(0-1) 0 Disabled 1 Enabled	0 Disabled	It can circulate pre-lubrication for genset after setting enabled.	
50. Pre-lubrication Interval	(0-7200)min	300	It can set circulate period after circulate pre-lubrication.	
51. Pre-lubrication Time 🦯	(0-7200)s	300	The time of each pre-lubrication.	
52. Idle Set	( <mark>0-2</mark> 000)r/min	700	When the controller is speed regulating automatically, the controller needs a stable rotate speed value.	
53. Dead Band	(0-10.0)%	1.0	Relay automatic speed regulation setting.	
54. Gain	(0-100)%	10	Note: as rated idle percent (in no working	
55. R <mark>esponse</mark>	0.25-4.00	0.50	area idle); as rated speed percent (in high	
56. Stability	(0.05-1.60)s	1.0	speed ).	
57. Speed Wire Break	(0-1) 0 Disabled 1 Enabled	0 Disabled	It can detect engine speed sensor wire break if enabled.	
58. Device ID	(1-254)	1	RS485 Comm. Address.	
59. Language Select	(0-1) 0: Chinese 1: English	0: Chinese	Language selections.	
60. Password Set	(0-65535)	00318	Password of parameter setting.	
61. DOUT16 Enable	(0-1)	0 Disabled	If DOUT16 module is needed to expand, this setting enabled is needed.	
62. HMC6000RM Module Enable	(0-1)	0 Disabled	If HMC6000RM module is needed to expand, this setting enabled is needed.	
63. RPU560A Enable (0-1)		0: Disabled	If RPU560A module is needed to expand,	



Parameter	Range	Default	Remarks
			this setting enabled is needed.
64. Expand Baud Set	(0-1) 0: 250kbps 1: 125kbps	0: 250kbps	CANBUS port communication Baud rate.
65. HMP300 Module Enable	(0-1) 0:Disabled 1:Enable	0: Disabled	If HMP300 module is needed to expand, this setting enabled is needed.
66. HMC9800RM Module Enable	(0-1) 0:Disabled 1:Enable	0: Disabled	If HMC9800RM module is needed to expand, this setting enabled is needed. (HMC6000A 2 does not have this function)
67. Self-check Type	(0-1) 0:Self-Check Mode 1 1: Self-check Mode 2	0: Self-check Mode 1	When self-check is set as 1, it can test alarm by connecting with corresponding sensor with no rotated speed after self-check is active; when self-check is set as 2, it can test alarm with system auto-regulating the sensor after self-check is active.
68. Date & Time			Date &Time setting.
69. Water Temp. Sensor set (Resistance input)	See 8.3. Sensor functional configuration Note: Resistance input measuring range is not applicable.		Water temperature sensor setting.
70. Oil Temp. Sensor set (Resistance input)	See 8.3. Sensor functional configuration Note: R Resistance input measuring range is not		Oil temperature sensor setting.
71. Oil Pressure Sensor set (Resistance/voltage/current input)	applicable. See 8.3. Sensor functional configuration Note: Resistance input measuring range is not applicable.		Oil pressure sensor setting.
72. Flexible sensor 1 Set (Resistance/voltage/current input)	See 8.3. Sensor functional configuration <b>Note:</b> Resistance input measuring range is not applicable.		Flexible sensor1 setting.
73. Flexible sensor 2 Set (Resistance/voltage/current input)	See 8.3. Sensor functional configuration <b>Note:</b> Resistance input measuring range is not applicable.		Flexible sensor2 setting.
74. Flexible sensor 3 Set (Resistance/voltage/current input)	See 8.3. Sensor functional configuration Note: Resistance input measuring range is not		Flexible sensor3 setting.



Parameter	Range	Default	Remarks
	applicable.		
75. Input 1 Set	(0-50)	18: Local Mode IN	See table 8.1.2.
76. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
77. Input 2 Set	(0-50)	19: Remote Mode IN	See table 8.1.2.
78. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
79. Input 3 Set	(0-50)	0: Not Used	See table 8.1.2.
80. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
81. Input 4 Set	(0-50)	0: Not Used	See table 8.1.2.
82. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
83. Input 5 Set	(0-50)	0: Not Used	See table 8.1.2.
84. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
85. Input 6 Set	(0-50)	0: Not Used	See table 8.1.2.
86. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
87. Input 7 Set	(0-50)	20: Remote Start Input	See table 8.1.2.
88. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
		See table 8.1.2.	
90. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
91. Input 9 Set	(0-50)	23: Override Mode	See table 8.1.2.
92. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
93. Input 10 Set	(0-50)	11: Fuel Leakage Input	See table 8.1.2.
94. Active type	(0-1)	0: Close Activate	Set up input port active of close or open.
95. Output 1 Set (0-100)		0: Not Used	See table 8.2.2.
96. Output type	(0-1)	0: Open	Set up output port be always open or always close.
97. Output 2 set	(0-100)	0: Not Used	See table 8.2.2.
98. Output type	(0-1)	0: Open	Set up output port be always open or always close output.
99. Output 3 set (0-100)		0: Not Used	See table 8.2.2.
100. Output type	(0-1)	0: Open	Set up output port be always open or always close output.
101. Output 4 set	(0-100)	0: Not Used	See table 8.2.2.



Parameter	Range	Default	Remarks
102 Output type	102. Output type (0-1) 0: 0		Set up output port be always open or always
102. Output type	(0-1)	0: Open	close output.
103. Output 5 set	(0-100)	0: Not Used	See table 8.2.2.
104 Output type	(0,1)	0: 0000	Set up output port be always open or always
104. Output type	(0-1)	0: Open	close output.
105. Output 6 set	(0-100)	0: Not Used	See table 8.2.2.
106. Output type	(0-1)	0: Open	Set up output port be always open or always
Too. Output type	(0-1)	0. Open	close output.
107. Output 7 set	(0-100)	0: Not Used	See table 8.2.2.
108. Output type	(0-1)	0: Open	Set up output port be always open or always
Too. Output type	(0-1)	0. Open	close output.
109. Output 8 set	(0-100)	0: Not Used	See table 8.2.2.
110. Output type	(0-1)	0: Open	Set up output port be always open or always
	(0-1)	0. Open	close output.
111. Output 9 set	(0-100)	0: Not Used	See table 8.2.2.
112. Output type	(0-1)	0: Open	Set up output port be always open or always
	(0-1)	0. Open	close output.
113. Output 10 set	(0-100)	0: Not Used	See table 8.2.2.
114. Output type	(0-1)	0: Open	Set up output port be always open or always
	(01)	0. Open	close output.
115. Output 11 set	(0-100)	0: Not Use <mark>d</mark>	See table 8.2.2.
116. Output type	(0-1)	0.0.0	Set up output port be always open or always
TTO. Output type	(031)	0: Open	close output.
117. Output 12 set	(0-100)	0: Not Used	See table 8.2.2.
118. Output type	(0 1)	0: Open	Set up output port be always open or always
110. Output type	(0-1)	0. Open	close output.

**Note:** The aux. input port 1~10 are corresponding with the input port A~J on the back plate of the controller.

**Note:** The aux. output port 1~12 are corresponding with the output port A~L on the back plate of the controller.

▲ Note: The Flexible sensor 1~3 are corresponding with the sensor A~C on the back plate of the controller.



# 8 INPUT/OUTPUT PORT CONFIGURATION

# 8.1 AUXILIARY INPUT 1~10 FUNCTIONAL CONFIGURATION

### 8.1.1 DIGITAL INPUT PORT CONFIGURATION

## **Table 9 Digital Input Port Definition**

No.	Settings	Contents	Description
1	Feature Set	(0- 50)	See 8.1.2 Input Port Functions
2	Active type	(0-1)	0: Close Activate 1: Open Activate
3	Active Range	(0-3)	0: From Safety on 1: From Crank 2: Always 3: Never
4	Action	(0-2)	0: Warning 1: Shutdown 2: Indication
5	Input Delay	(0-20.0)s	
6	Displayed string	User-defined input port names	20 English symbols or 10 Chinese characters

#### 8.1.2 INPUT PORT FUNCTIONS

#### **Table 10 Input Ports Function Definition**

No.	Function	Description
0.	Not Used	Not used.
1.	Custom	Users configured input port settings.
2.	Alarm Mute	Can prohibit "Audible Alarm" output when it is active.
3.	Reset Alarm	Can reset all alarms when input is active.
4.	Pre-lubricate	If output is set as pre-lubrication output, the relay disconnects after the set pre-lubrication delay.
5.	Reserved	
6.	Panel Lock	All buttons in panel is inactive except $$ and $$ when input is active.
7.	Quick Start	Cranking will start directly (without preheating) when the input is active.
		Genset starts when active and stops when inactive.
		Note: only one of two start/stop control ways (remote
8.	Remote Start/Stop	start/stop input, and remote starts input and remote
		stop input) can be selected, and cannot select at the same time.
9.	Auto Mode IN	When the input is active, enter into auto mode, the local mode and remote mode is inactive and start/stop can only be achieved via input port.
10.	Turning Chain	Start inhibition when the input is active.
11.	Fuel Leakage Input	When the input active, alarm initiate if fuel leak occurs.
12.	Water Press. Low	Connect to digital input of sensor.
13.	Water Level Low	Connect to digital input of sensor.
14.	Oil Level Low	Connect to digital input of sensor.
15.	Water Temp. High IN	Connect to digital input of sensor.
16.	Oil Temp. High IN	Connect to digital input of sensor.
17.	Oil Pressure Low IN	Connect to digital input of sensor.
18.	Local Mode IN	The genset is in local mode when active.
19.	Remote Mode IN	The genset is in remote mode when active.
20.	Remote Start Input	When remote start input is active in Remote Control Mode, controller initiate start command.
21.	Stop Input	When stop input is active in Remote Control Mode or



No.	Function	Description
		Auto Mode, controller initiate stop command.
22.	Auto Start Input	When auto start input is active in Auto Mode, controller initiate start command.
23.	Override Mode	When over ride mode input is active, only over speed stop and emergency stop are available.
24~50	Reserved	

**A** Note: The name of the input ports 1~10 only can be configured via PC software.

#### 8.2 OUTPUT PORT DEFINITION

#### 8.2.1 DIGITAL OUTPUT DEFINITION CONTENTS

#### Table 11 Digital Output Port Definition Content

No.	Items	Contents	Note
1	Output Function	(0-100)	
	Configuration		
2	Effective ways	0 Open 1 Close	
		Bit1: Standby	
		Bit2: Preheat	
		Bit3: Fuel Output	
		Bit4: Start	
		Bit5: Crank Rest Time	
		Bit6: Safety Delay	
		Bit7: Start Idle	
3	Effective duration	Bit <mark>8: High</mark> Speed Warm Up	
		Bit9: Wait to Load	
		Bit10: Normally Working	
		Bit11: Cooling	
		Bit12: Stop Idle	
		Bit13: ETS	
		Bit14: Wait for Stop	
		Bit15: Fail to Stop	
5	Delay output time	(0-100.0)s	
6	Output time	(0-3600)s	

#### 8.2.2 OUTPUT PORT 1-12 FUNCTION DEFINITION

# Table 12 Output Port 1-12 Function Definition

No.	Items	Description
0.	Not Used	This port is not used.
1.	Custom	See Table 11.
2.	Air Flop	Action when over speed shutdown and emergence stop. Air
Ζ.	Air Flap	flap can be closed.
		Action when warning and shutdown. It can be connected
3.	Audible Alarm	enunciator externally. When "alarm mute" configurable input
		port is active, it can remove the alarm.
4.	Crank Output	Action when genset is starting and disconnect when crank
4.		success.

**Smart**Gen

No.	Items	Description		
5.	Fuel Output	Action when genset is starting and disconnect when stop is		
0.		completed.		
6.	ETS Hold	Action period: ETS hold delay.		
7.	Reserved			
8.	Reserved			
9.	Loss of Speed	After safety on delay, the controller active when the engine		
		speed is 0.		
10.	Pre-lubricate	The controller output when the engine is in standby mode		
. 0.		(user-defined output delay) if pre-lubrication input is active.		
11.	Override Output	The controller output when it is in Over ride mode.		
12.	Ready Go(1)	The controller output when it is in standby mode and no		
12.		alarms.		
13.	Heater Control	It is controlled by heating temperature sensor's limited		
15.		threshold.		
		Action from "crank delay" to "start idle delay" and from "stop		
14.	Idle Control	idle delay" to "wait for stop delay". When in local mode, idle		
		control is unavailable.		
15.	Common Alarm	Action when genset common warning and common shutdown		
15.	Common Alann	alarms occur.		
16.	Common Shutdown	Action when common shutdown alarm.		
17.	Common Warn	Action when common warning alarm.		
18.	Input 1 Active	Ac <mark>tion w</mark> hen digital input port 1 is active.		
19.	Input 2 Active	Action when digital input port 2 is active.		
20.	Input 3 Active	Action when digital input port 3 is active.		
21.	Input 4 Active	Action when digital input port 4 is active.		
22.	Input 5 Active	Action when digital input port 5 is active.		
23.	Input 6 Active	Action when digital input port 6 is active.		
		The engine outputs when the speed over 500r, stops when the		
24.	Start Successful Output	speed less than 100r.		
		The engine outputs when the speed over 85% of rated		
25.	Normal Running Output	requirements, stops when less than 75% of rated		
		requirements.		
26.	Remote Mode Output	The controller output in remote control mode.		
27.	Local Mode Output	The controller output in local mode.		
28.	Ready Go(2)	Output when there is no shutdown alarm.		
		Action when the controller detects communication failure with		
29.	DOUT16 Com Fail	DOUT16. (3s overtime)		
30.	Shutdown Output	The controller output when it is shutdown mode.		
31.	Power 1 Under Volt	Action when the controller detects that the power 1 voltage		
51.		has fallen below the set value.		
32.	Power 1 Over Volt	Action when the controller detects that the power 1 voltage		
52.		has exceeded the set value.		
		Action when under speed warning.		
33.	Under Speed Warn	Action when under speed warning.		



No.	Items	Description		
35.	Over Speed Warn	Action when over speed warning.		
36.	Over Speed Stop	Action when over speed shutdown alarm.		
37.	Emergency Stop	Action when emergency stop alarm.		
38.	Charge Alt Fail	Action when charge failure warning.		
39.	Failed To Start	Action when failed start alarm.		
40.	Failed To Stop	Action when failed stop alarm.		
41.	Reserved			
42.	Water Temp. Open	Action when water temperature sensor is open circuit.		
43.	Water Temp. High Warn	Action when high water temperature sensor warning alarm.		
44.	Water Temp. High Stop	Action when high water temperature sensor shutdown alarm.		
45.	Oil Temp. Open	Action when oil temperature sensor is open circuit.		
46.	Oil Temp. High Warn	Action when high oil temperature sensor warning alarm.		
47.	Oil Temp. High Stop	Action when high oil temperature sensor shutdown alarm.		
48.	Oil Pressure Open	Action when oil pressure sensor is open circuit.		
49.	Oil Pressure Low Warn	Action when low oil pressure sensor warning alarm.		
50.	Oil Pressure Low Stop	Action when low oil pressure sensor shutdown alarm.		
51.	Sensor 1 Open	Action when Flexible sensor 1 is open circuit.		
52.	Sensor 1 Warn	Action when Flexible sensor 1 warning alarm.		
53.	Sensor 1 Shutdown	Action when Flexible sensor 1 shutdown alarm.		
54.	Sensor 2 Open	Action when Flexible sensor 2 is open circuit.		
55.	Sensor 2 Warn	Action when Flexible sensor 2 warning alarm.		
56.	Sensor 2 Shutdown	Action when Flexible sensor 2 shutdown alarm.		
57.	Reserved	Reserved		
58.	RPU560A Com Fault	Action when the controller detects communication failure with		
56.	RP0500A Colli Fault	RPU560A safeguard module. (3s overtime)		
59.	RPU560A Power 1 Fault	Security module output when power1 fault.		
60.	RPU560A Power 2 Fault	Security module output when power2 fault.		
		When the controller is in idle mode, if speed doesn't arrive at		
_		rated idle, it will output when speed is rising and auto		
		disconnect when speed arrives at rated idle.		
61.	Rise Speed	When the controller is hi-speed running, if speed doesn't arrive		
		at rated rotate speed, it will output when speed is rising and		
		auto disconnect when speed arrives at rated rotate speed.		
		Note: Active only when controller is in remote/auto mode.		
		When the controller is in idle mode, if speed exceeds rated		
		idle, it will output when speed is dropping and auto disconnect		
		when speed arrives at rated idle.		
62.	Drop Speed	When the controller is hi-speed running, if speed exceeds		
		rated rotate speed, it will output while speed is dropping and		
		auto disconnect when speed arrives at rated rotate speed.		
		Note: Active only when controller is in remote/auto mode.		
63.	Sensor 3 Open	Action when Flexible sensor 3 is open circuit.		
64.	Sensor 3 Warn	Action when Flexible sensor 3 warning alarm.		
65.	Sensor 3 Shutdown	Action when Flexible sensor 3 shutdown alarm.		



No.	Items	Description		
66.	Fuel Leakage	Output when this alarm is active.		
67	Dower 2 Under Volt	Output when the controller detects power 2 voltage is lower		
67.	Power 2 Under Volt	than set value.		
()	Power 2 Over Volt	Output when the controller detects power 2 voltage is upper		
68.		than set value.		
69.	Lamp Test Output	Output while lamp testing.		
70~	Decemied	Decented		
100	Reserved	Reserved		

#### 8.3 SENSOR FUNCTIONAL CONFIGURATION

# 8.3.1 SENSOR CONFIGURATION

# Table 13 Controller Sensor Configuration

No.	Settings	Contents	Remarks
		(0-3)	Types such as "Water Temperature
		0: Not Used	Sensor", "Oil Temperature Sensor",
1.	Sensor type	1: Oil Pressure Sensor	and "Oil Pressure Sensor" are not
		2: Temperature Sensor	optional and are fixed temperature or
		3: Fuel Level Sensor	pressure.
2.	Curve Type	Curve types list	See 8.3.2/8.3.3/8.3.4 curve lists.
3.	Alarm speed	(0-200)%	Alarm and test when the engine speed
5.	Alann speed	(0-200)/8	has exceeded the set value.
			Active when current of sensor is
			between (4~20)mA. Corresponding
4.	Range	(0-6000)	unit of pressure sensor is kPa;
			Corresponding unit of level sensor
			is %.
		Temperature 0: °C	
		1: °F	The units displayed on LCD. After
5.	Display Units	Pressure 0: kPa	selection of units, the displayed data
5.		1: bar	will automatically convert according
		2: psi	to units.
		Fuel level unit fixed as "%"	
		(0-1)	
6.	High Shutdown Enable	0: Enable	
		1: Disable	
7.	Set Value	(0-6000)	
8.	Delay	(0-3600)s	
		(0-1)	
9.	Low Shutdown Enable	0: Enable	
		1: Disable	
10.	Set Value	(0-4000)	
11.	Delay	(0-3600)s	
12.	Sensor High Warn Enable	(0-1)	



No.	Settings	Contents	Remarks
		0: Enable	
		1: Disable	
13.	Set Value	(0-6000)	
14.	Return Value	(0-6000)	
15.	Delay	(0-3600)s	
		(0-1)	
16.	Low Warn Enable	0: Enable	
		1: Disable	
17.	Set Value	(0-4000)	
18.	Return Value	(0-4000)	
19.	Delay	(0-3600)s	
20.	First point X (Resistance)	Resistance type (not PT100)	
21.	Second point X (Resistance)	Resistance type (not PT100)	
22.	Third point X (Resistance)	Resistance type (not PT100)	
23.	Fourth point X (Resistance)	Resistance type (not PT100)	
24.	Fifth point X (Resistance)	Resistance type (not PT100)	
25.	Sixth point X (Resistance)	Resistance type (n <mark>ot P</mark> T100)	
26.	Seventh point X (Resistance)	Resistance type (not PT100)	Sensor curve is user-defined
27.	Eighth point X (Resistance)	Resistance type (not PT100)	X axis: 8 Y axis: 8.
28.	First point Y (Value)	Resistance type (not PT100)	
29.	Second point Y (Value)	Resistance type (not PT100)	
30.	Third point Y (Value)	Resistance type (not PT100)	
31.	Fourth point Y (Value)	Resistance type (not PT100)	
32.	Fifth point Y (Value)	Resistance type (not PT100)	
33.	Sixth point Y (Value)	Resistance type (not PT100)	
34.	Seventh point Y (Value)	Resistance type (not PT100)	
35.	Eighth point Y (Value)	Resistance type (not PT100)	
36.	User-defined string	User-defined sensor names	Only can be set via upper computer software.



#### 8.3.2 TEMPERATURE CURVES

No.	Contents	Remarks
0	Not Used	
1	PT100	
2	Custom Res Curve	
3	VDO	
4	CURTIS	
5	VOLVO-EC	
6	DATCON	The input range of year defined registered is between
7	SGX	The input range of user-defined resistance is between
8	SGD	$(0-1000)\Omega$ . The factory defaults of water temperature
9	SGH	sensor and oil temperature sensor are PT100 sensors.
10	Reserved	
11	Cu50	
12	Reserved	
13	Reserved	
14	Reserved	
15	Reserved	

#### Table 14 Temperature Curve List

**Δ** Note: PT100 Resistance type temperature sensor division value is fixed set as 0.385 (0.385Ω

corresponds to 1 °C).

#### 8.3.3 PRESSURE CURVES

# Table 15 Pressure Curve List

No.	Contents	Remarks
0	Not Used	
1	(4~20)mA	
2	Custom Res Curve	
3	VDO 10Bar	
4	CURTIS	
5	Volt (0.5V-4.5V)	
6	DATCON 10Bar	The input range of User defined registeres is between
7	SGX	The input range of User-defined resistance is between
8	SGD	$(0-1000)\Omega$ . The factory default of oil pressure sensor is $(4-20)mA$ sensor.
9	SGH	(4-20)ITIA SEIISOI.
10	Custom Volt Curve	
11	Reserved	
12	Reserved	
13	Reserved	
14	Reserved	
15	Reserved	

**Note:** There is no need to set curve type but range if the pressure sensor is current type.



# 8.3.4 FUEL LEVEL CURVES

#### Table 16 Fuel Level Curve List

No.	Contents	Remarks				
0	Not Used					
1	(4~20)mA					
2	Custom Res Curve					
3	SGD					
4	SGH					
5	Reserved					
6	Reserved	The default of annountime depends have first level as more				
7	Reserved	The default of sensor type doesn't have fuel level senso				
8	Reserved	Please chose one of Flexible sensor 1/2/3 to use if need				
9	Reserved	to.				
10	Reserved					
11	Reserved					
12	Reserved					
13	Reserved					
14	Reserved					
15	Reserved					

**Note:** There is no need to set curve type but range if the pressure sensor is current type.



#### 9 PARAMETER SETTING

#### 9.1 MATTERS NEEDED ATTENTION

Press the button for 1 second after start the controller, and then enter into parameter configuration and controller info selection menu, in which enter parameter configuration menu needs to input correct password. The default password is 00318.

Please contact with manufacturer when forgets the password or need to correct the resistance/current/voltage value.

- Please modify the controller internal parameters in standby mode(such as starting successfully condition selections, auxiliary inputs, output port configuration, time delay, etc), otherwise the alarm stop or other abnormal phenomena may occur.
- High sensor alarm threshold value must be bigger than the low alarm threshold, otherwise they
  will both alarm simultaneously.
- Over speed threshold value must be bigger than under speed threshold, otherwise there will be either overspeed or underspeed simultaneously.
- When setting the condition of successful start, the start speed threshold value is supposed to be set lower as possible for quick disconnection of starter.
- Auxiliary input port 1-10 cannot be set to the same project, otherwise correct function cannot arrive. Auxiliary output port 1-12 can be set to the same project.

#### 9.2 SENSOR SETTING CLARIFICATION

- When reselect the sensors, the standard value of the selected sensor will be selected. If temperature sensor default is set to PT100, sensor curve will be the curve of PT100. If it is set to SGD (120°C resistance), sensor curve will be the curve of SGD.
- If standard sensor curve is mismatching with sensor in using, "User-defined sensor "could be chosen, then input user-defined sensor curve.
- When inputting sensor curve, X (resistance) must be input in accordance with the order of growing up, otherwise mistakes will occur.
- Can set ordinate of front several points or last several points to the same. As shown in below:

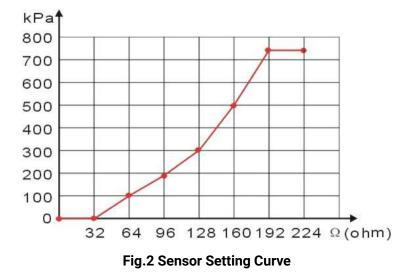
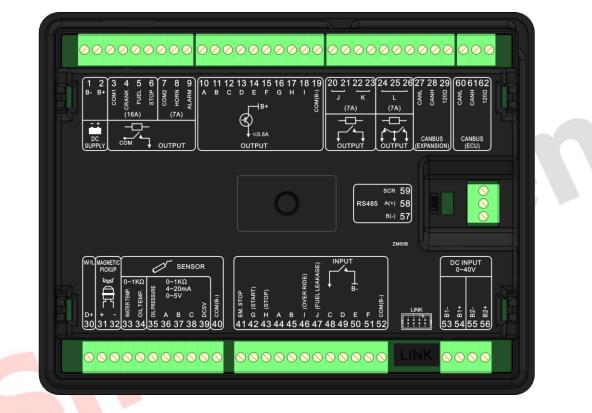




Table 17 Normal Pressure Unit Conversion Table	е
--	---

	N/m² Pa	kgf/cm <sup>2</sup>	bar	psi
1Pa	1	$1.02 \times 10^{-5}$	1x10 <sup>-5</sup>	$1.45 \times 10^{-4}$
1kgf/cm <sup>2</sup>	9.8x10 <sup>4</sup>	1	0.98	14.2
1bar	1x10⁵	1.02	1	14.5
1psi	6.89x10 <sup>3</sup>	7.03x10 <sup>-2</sup>	6.89x10 <sup>-2</sup>	1

# 10 BACK PANEL



## Fig.3 HMC6000A 2 Controller Back Panel

# **Table 18 Terminal Connection Description**

Icon	No.	Function	Cable Size	Description
- +	1.	DC input B-	2.5mm <sup>2</sup>	DC power supply negative input.
	2.	DC input B+	2.5mm <sup>2</sup>	DC power supply positive input.
	3.	COM1 Relay common port	1.5mm <sup>2</sup>	
	4.	Start relay	1.5mm <sup>2</sup>	Connect to COM1 relay output;
	5.	Fuel relay	1.5mm <sup>2</sup>	rated 16A
сом	6.	Stop relay	1.5mm <sup>2</sup>	
ŧ		COM2 Relay common port	1.0mm <sup>2</sup>	Connect to COM2 relay output:
	8.	Audio Alarm Relay	1.0mm <sup>2</sup>	Connect to COM2 relay output; rated 16A
	9.	Common Alarm Relay	1.0mm <sup>2</sup>	
	10.	Aux. output 1(A)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.



Icon	No.	Function	Cable Size	Description
В+	11.	Aux. output 2(B)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.
æ	12.	Aux. output 3(C)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.
Ϋ́	13.	Aux. output 4(D)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.
Ļ	14.	Aux. output 5(E)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.
	15.	Aux. output 6(F)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.
	16.	Aux. output 7(G)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.
	17.	Aux. output 8(H)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.
	18.	Aux. output 9(I)	1.0mm <sup>2</sup>	B+ output, rated 0.5A.
	19.	COM(B-)	1.0mm <sup>2</sup>	
	20.	Aux. output 10(J)	1.0mm <sup>2</sup>	
	21.		1.0mm <sup>2</sup>	Free volts contact always open; Rated
	22.	Aux. output 11(K)	1.0mm <sup>2</sup>	current: 7A; volt free output.
	23.		1.0mm <sup>2</sup>	
	24.		1.0mm <sup>2</sup>	Free volts contact always open; Rated
	25.	Aux. output 12(L)	1.0mm <sup>2</sup>	current: 7A; volt free output.
+ + +	26.		1.0mm <sup>2</sup>	current. 7A, voit nee output.
CANBUS	27.	CAN(L) (EXPANSION)	0.5mm <sup>2</sup>	Used for connect to remote control and
(EXPAN-	28.	CAN(H) (EXPANSION)	0.5mm <sup>2</sup>	extended output module. If connect CAN(L) to $120\Omega$ , then there is no need to
SION)	29.	120Ω (EXPANSION)	0.5mm <sup>2</sup>	external connect 120Ω resistor.
W/L	30.	D+ Charge input	1.0mm <sup>2</sup>	Charging generator D+ terminal input; Ground connected is not allowed.
L.	31.	MP1 (Magnetic pickup+)	0.5mm <sup>2</sup>	Connect to speed sensor; Using shielding wire is recommended.
D STA	32.	MP1 (Magnetic pickup-)	0.5mm	MP1(-) internal connect B
	33.	Water Temperature Sensor	ature Sensor 1.0mm <sup>2</sup>	Water temperature sensor
		Input		input(resistance)
	34.	Oil Temperature Sensor	1.0mm <sup>2</sup>	Oil temperature sensor
		Input		input(resistance).
	35.	Oil Pressure Sensor Input	1.0mm <sup>2</sup>	Oil pressure sensor
		-		input(resistance/current
~	36.	Flexible sensor 1	1.0mm <sup>2</sup>	
				(resistance/current/voltage)
	37.	Flexible sensor 2	1.0mm <sup>2</sup>	User configure
				(resistance/current/voltage)
	38.	Flexible sensor 3	1.0mm <sup>2</sup>	User configure (resistance/current/voltage)
	39.	DC5V	1.0mm <sup>2</sup>	Supply power for voltage type sensors.
	39.			Input common port. Connect to (B-)
	40.	COM(B-) input	1.0mm <sup>2</sup>	inside
	41.	Emergency Shutdown Input	0.5mm <sup>2</sup>	Controller shutdown urgently if input

ideas for power				
lcon	No.	Function	Cable Size	Description
INPUT				active.
	42.	Start (G)	0.5mm <sup>2</sup>	Digital input 7
	42.		0.511111	Default Set: Remote start input.
• В-	43.	Stop (H)	0.5mm <sup>2</sup>	Digital input 8
	40.		0.01111	Default Set: Stop input.
	44.	Aux. Input1 (A)	0.5mm <sup>2</sup>	User configure
			0.01111	Default Set: Local Mode input.
	45.	Aux. Input2 (B)	0.5mm <sup>2</sup>	User configure
			0.01111	Default Set: Remote Mode input.
	46.	Override (I)	0.5mm <sup>2</sup>	Digital input 9
	<del>т</del> 0.		0.01111	Default Set: Override input.
	47.	Fuel Leakage (J)	0.5mm <sup>2</sup>	Digital input 10
	ч <i>7</i> .			Default Set: Fuel leakage input.
	48.	Aux. input 3 (C)	0.5mm <sup>2</sup>	User configure
	49.	Aux. input 4 (D)	0.5mm <sup>2</sup>	User configure
	50.	Aux. input 5 (E)	0.5mm <sup>2</sup>	User configure
	51.	Aux. input 6 (F)	0.5mm <sup>2</sup>	User configure
	52.	. COM(B-) input	1.0mm <sup>2</sup>	Input common port, connect to (B-)
	52.			inside
Power A	53.	B1-	1.0mm <sup>2</sup>	Power supply A negative pole
Input	54.	B1+	1.0mm <sup>2</sup>	Power supply A positive pole
Power B	55.	B2-	1.0mm <sup>2</sup>	Power supply B negative pole
Input	56.	B2+	1.0mm <sup>2</sup>	Power supply B positive pole
	57.	RS485-(B)	0.5mm <sup>2</sup>	PC programming and monitoring port
RS485	58.	RS485+(A)	0.5mm <sup>2</sup>	(isolation type). Its single end earthed.
	<b>59</b> .	RS485 Shield Ground	0.5mm <sup>2</sup>	(isolation type). Its single end eartied.
	60.	CAN(L)	0.5mm <sup>2</sup>	Used for connect to ECU of engine with
	00.	(ECU)	0.51111	J1939 interface. If connect CAN(L) to
CANBUS	61.	CAN(H)	0.5mm <sup>2</sup>	$120\Omega$ , then there is no need to external
(ECU)	01.	(ECU)	0.000	connect $120\Omega$ resistor.
62		62. (Ξου)	0.5mm <sup>2</sup>	(HMC6000A is unavailable)
	02.	(ECU)	0.5mm²	
LINK				Enables connection to PC monitoring
				software.

▲ SmartGen

**Note:** It is strictly prohibited to take out start battery when the engine is running. Failure to do so can create excessive DC input voltage and result in damage of destruction of equipment!

**Note:** Compared with HMC6000A rear panel, HMC6000A 2 has a CANBUS (ECU) interface.



#### **11 COMMUNICATION AND CONNECTION**

#### 11.1 RS485 AND LINK COMMUNICATION

HMC6000A/HMC6000A 2 genset controller has RS485 port and Link port which allows the controller to connect to open-type LAN. RS485 and Link applies ModBus communication protocol with the help of PC or DAS (Data Acquisition Systems) operational software provides easy to use marine engine monitoring system management scheme and enables remote control, remote measurement and remote communication.

#### 11.2 CANBUS (EXPANSION) BUS COMMUNICATION

Various expansion modules can be connected to the controller via CANBUS (EXPANSION) port.

- DOUT16 Digital output module: The module connects to the main controller via CANBUS port. Main controller transfers the output condition data of digital output module to module to handle via CANBUS. All parameters of digital output port can be configured via main controller.
- HMC6000RM Remote control module: Remote control module can achieve control operations such as starting engine, stopping engine, etc. All kinds of parameters and records of the engine real-time display on remote controller.
- RPU560A Security module: The module connects to the main controller via CANBUS port. If security module receives no signal from the main controller for more than 1 second and the main controller failure input deactivates, security module will take over engine control; after that the engine will be stopped only by shutdown input or in case of overspeed. Module input function, output function and overspeed alarm threshold are user-set.

**Note:** Remote control module can only be used in remote mode of the engine; in local mode remote control

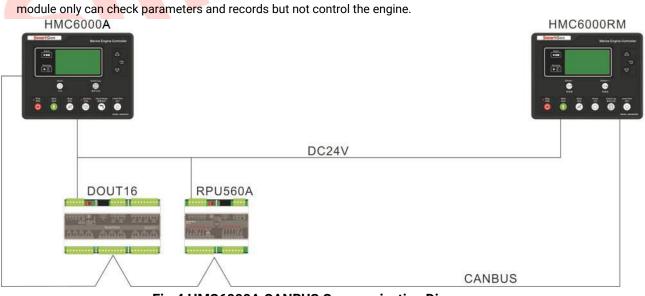


Fig.4 HMC6000A CANBUS Communication Diagram



#### 11.3 CONTROLLER AND ENGINES CONNECTION (EXPANSION CANBUS)

A large number of J1939 engines can be controlled by the controller via CANBUS (ECU) port. Besides, at the same time users also can connect expansion module which makes it convenient and suitable for different working environments.

#### **Note:** HMC6000 does not have this function.

#### 11.3.1 CUMMINS ISB/ISBE

#### Table 19 Fuel Start Wiring Connection

Terminals of controller	Connector B	Remarks
Fuel relay output	39	
Start relay output	-	Connect to starter coil directly.
Programmable output port 1	Expand 30A relay, battery voltage of terminal 01,07,12,13 are supplied by relay.	ECU power; set programmable output 1 as "ECU power".

#### Table 20 9-Pin Connector Wiring Connection

Terminals of controller	9 pin connector	Remarks
CAN(H) (ECU)	SAE J1939 signal	Impedance 120Ω connecting line is recommended.
CAN(L) (ECU)	SAE J1939 return	Impedance 120Ω connecting line is recommended.

#### Engine type: Cummins ISB

#### 11.3.2 CUMMINS QSL9

Compatible with CM850 engine controller module.

#### **Table 21 Fuel Start Wiring Connection**

Terminals of controller	50 pin connector	Remark
Fuel relay output	39	
Start relay output	-	Connect to starter coil directly.

#### Table 22 9-Pin Connector Wiring Connection

Terminals of controller	9 pin connector	Remark
CAN(H) (ECU)	SAE J1939 signal-C	Impedance $120\Omega$ connecting line is recommended.
CAN(L) (ECU)	SAE J1939 return-D	Impedance $120\Omega$ connecting line is recommended.

Engine type: Cummins-CM850



# 11.3.3 CUMMINS QSM11

Compatible with CM750 engine controller module. Engine types: QSM11 G1, QSM11 G2

## Table 23 Fuel Start Wiring Connection

Terminals of controller	C1 connector	Remark
Fuel relay output	5&8	
Start relay output	-	Connect to starter coil directly.

#### Table 24 3-Pin Connector Wiring Connection

Terminals of controller	3 pin data link connector	Remark
CAN(H) (ECU)	A	Impedance $120\Omega$ connecting line is
		recommended.
CAN(L) (ECU)	В	Impedance $120\Omega$ connecting line is
		recommended.

#### Engine type: Cummins ISB

#### 11.3.4 DETROIT DIESEL DDEC III / IV

#### Table 25 Engine Wiring Connection

Terminals of controller	Engine CAN port	Remark
Fuel relay output	Expand 30A relay; battery voltage of ECU is supplied by relay	
Start relay output	-	Connect to starter coil directly.
CAN(H) (ECU)	CAN(H)	Impedance $120\Omega$ connecting line is recommended.
CAN(L) (ECU)	CAN(L)	Impedance $120\Omega$ connecting line is recommended.

#### Engine type: Common J1939

#### 11.3.5 **DEUT**Z EMR2

#### **Table 26 Engine Wiring Connection**

Terminals of controller	F connector	Remark
Fuel relay output	Expand 30A relay, battery voltage of terminal 14 is supplied by relay. Fuse is 16A.	
Start relay output	-	Connect to starter coil directly.
-	1	Connect to battery negative.
CAN(H) (ECU)	12	Impedance $120\Omega$ connecting line is recommended.
CAN(L) (ECU)	13	Impedance $120\Omega$ connecting line is recommended.

#### Engine type: Volvo EDC4



#### 11.3.6 JOHN DEERE

#### Table 27 Engine Wiring Connection

Terminals of controller	21 pin connector	Remark
Fuel relay output	G, J	
Start relay output	D	
		Impedance 120Ω connecting line is
CAN(H) (ECU)	v	recommended.
	11	Impedance $120\Omega$ connecting line is
CAN(L) (ECU)	0	recommended.

#### Engine type: John Deere

#### 11.3.7 MTU MDEC

Compatible with MTU 2000 and 4000 series engines.

#### **Table 28 Engine Wiring Connection**

Terminals of controller	V1 connector	Demorte
Terminals of controller	X1 connector	Remark
Fuel relay output	BE1	
Start relay output	BE9	
CAN(H)(ECU)	G	Impedance 120Ω connecting line is
		recommended.
CAN(L)(ECU)	F	Impedance $120\Omega$ connecting line is
		recommended.

#### Engine type: MTU-MDEC-303

#### 11.3.8 PERKINS

Compatible with ADEM3/ ADEM4 engine control modules. Engine types: 2306, 2506, 1106, and 2806.

# Table 29 Engine Wiring Connection

Terminals of controller	Connector	Remark
Fuel relay output	1,10,15,33,34	
Start relay output	-	Connect to starter coil directly
CAN(H) (ECU)	31	Impedance $120\Omega$ connecting line is recommended.
CAN(L) (ECU)	32	Impedance $120\Omega$ connecting line is recommended.

Engine type: Perkins



# 11.3.9 SCANIA

Compatible with S6 engine control module. Engines: DC9, DC12, DC16.

#### Table 30 Engine Wiring Connection

Terminals of controller	B1 connector	Remark
Fuel relay output	3	
Start relay output	-	Connect to starter coil directly.
CAN(H) (ECU)	9	Impedance $120\Omega$ connecting line is recommended.
CAN(L) (ECU)	10	Impedance $120\Omega$ connecting line is recommended.

Engine type: Scania

#### 11.3.10 VOLVO EDC3

Compatible with such engines as TAD1240, TAD1241, and TAD1242.

#### Table 31 Fuel Start Wiring Connection

Terminals of controller	"Stand alone" connector	Remark
Fuel relay output	Н	
Start relay output	E	
Auxiliary output 1	Р	Set auxiliary output 1 as "Preheating until cranking" and set preheating time as 5 seconds.

#### Table 32 CANBUS Wiring Connection

Terminals of controller	"Data bus" connector	Remark	
CAN(H) (ECU)	1	Impedance $120\Omega$ connecting line is	
		recommended.	
CAN(L) (ECU)	2	Impedance $120\Omega$ connecting line is	
		recommended.	

Engine type: Volvo

#### 11.3.11 VOLVO EDC4

Compatible engine types are TD520, TAD520 (optional), TD720, TAD720 (optional), TAD721, and TAD722.

#### **Table 33 Engine Wiring Connection**

Terminals of controller	Connector	Remark
Fuel relay output	Expand 30A relay, battery volt of terminal 14 is supplied by relay. Fuse is 16A.	
Start relay output	-	Connect to starter coil directly.
	1	Connect to battery negative.
CAN(H) (ECU)	12	Impedance 120Ω connecting line is recommended.
CAN(L) (ECU)	13	Impedance 120Ω connecting line is recommended.



Engine type: Volvo EDC4

#### 11.3.12 VOLVO-EMS2

Compatible with the following Volvo engines: D9、D13、D16、EMS

#### **Table 34 Engine Wiring Connection**

Terminals of controller	Engine CAN port	Remark
	5	ECU power supply
Auxiliary output 2		Set auxiliary output 2 as "ECU Power
		Supply".
CAN(H) (ECU)	1(CAN H)	Impedance $120\Omega$ connecting line is
		recommended.
CAN(L) (ECU)	2(CAN L)	Impedance $120\Omega$ connecting line is
		recommended.

Input ports can be set with speed control function, auxiliary input port 1 can be set as speed up input, and auxiliary input port 2 can be set as speed down input. After the normal running, raise/drop speed functions can be achieved by digital input ports.

Engine type: Volvo-EMS2

#### 11.3.13 BOSCH

Compatible with BOSCH common rail electronic engines.

# Table 35 Engine Wiring Connection

Terminals of controller	42 pin engine port	Remark
Fuel relay output	1.40	Connect to engine ignition switch.
Start relay output	-	Connect to starter coil directly.
CAN(H) (EXPANSION)	1.35	Impedance $120\Omega$ connecting line is
		recommended.
CAN(L) (EXPANSION)	1.34	Impedance $120\Omega$ connecting line is
		recommended.

#### 11.3.14 **POWER WIRING CONNECTION**

#### **Table 36 Power Wiring Connection**

Battery	2 pin engine port	Remark
Battery negative	1	Wire size: 2.5mm <sup>2</sup>
Battery positive	2	Wire size: 2.5mm <sup>2</sup>

#### Engine type: BOSCH

Please contact us if you have any questions about controller and ECU connection.



# 12 HMC6000A 2 APPLICATION DIAGRAM

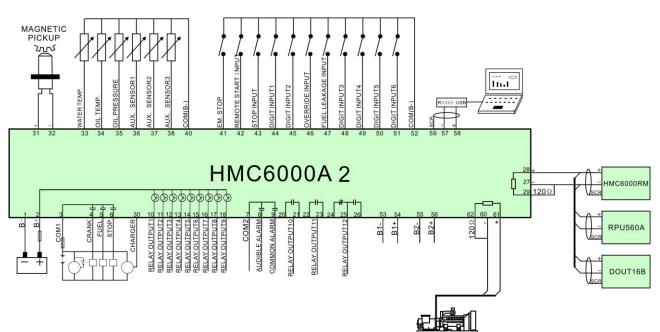


Fig.5 HMC6000A 2 Application Diagram



#### **13 COMMISSIONING**

Doing the following check before the system starting to run formally is recommended:

- Ensure all the connections are correct and wires diameter is suitable;
- Ensure that the controller DC power has fuse, controller's positive and negative connected to start battery are correct;
- Take proper action to prevent engine to crank success (e. g. Remove the connection wire of fuel valve). If checking is OK, make the start battery power on;
- Make the local mode active and then the controller enter into local mode. Press the Start button and the engine will start. If fail to start, genset will enter into ETS status automatically;
- Recover the action to prevent engine to crank success e. g. Connect wire of fuel valve), press start button again, and the engine will start. The engine will run from idle to formal if all works regularly. During this time, please watch the running status. If abnormal, stop engine and check all wires connection according to this manual;
- If there is any other question, please contact SmartGen's service.

#### 14 INSTALLATION

#### 14.1 FIXING CLIPS

Controller is panel built-in design; it is fixed by clips when installed.

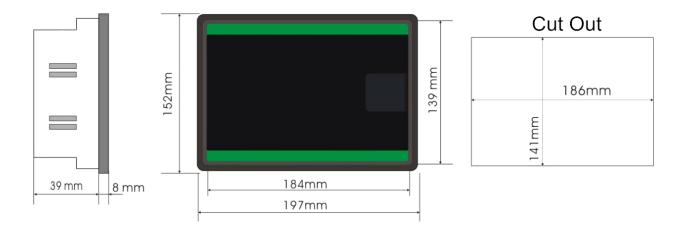
- Withdraw the fixing clip screw (turn anticlockwise) until it reaches proper position;
- Pull the fixing clip backwards (towards the back of the module) ensuring two clips are inside their allotted slots;
- Turn the fixing clip screws clockwise until they are fixed on the panel.
- **A** NOTE: Care should be taken not to over tighten the screws of fixing clips.



Fig.6 Fixing Clip Installation



#### 14.2 OVERALL DIMENSIONS AND CUTOUT DIMENSIONS



#### **Fig.7 Overall and Cutout Dimensions**

#### **15 INSTALLATION CAUTIONS**

#### 15.1 BATTERY VOLTAGE INPUT

HMC6000A/HMC6000A 2 controller can suit for widely range of battery voltage DC (8~35) V. Negative of battery must be connected with the engine shell. The diameter of wire which is from power supply to battery must be over 2.5mm<sup>2</sup>. If floating charge configured, please firstly connect output wires of charger to battery's positive and negative directly, then, connect wires from battery's positive and negative input ports in order to prevent charge disturbing the controller's normal working.

#### 15.2 SPEED SENSOR INPUT

Speed sensor is magnetic equipment which is installed on engine body for testing flywheel teeth number. 2 core shielding wire is used for the connection of the sensor and controller. The wire is supposed to be connected to 32 terminal of controller with one end and the other end hanging in the air. The other two signal lines connect separately to 31, 32 terminals. Speed sensor output voltage is supposed to be at AC (1-24) V (virtual value) when it is in full speed range, and AC12V (when in rated rotate speed) is recommended. When install the speed sensor, screw it to contact the flywheel firstly, inverse it with 1/3 circle, and then tighten the nut finally.

#### 15.3 OUTPUT AND EXPANSION RELAY

All outputs of controller are relay contact output type. If expansion relays are needed, please add freewheel diode to both ends of expansion relay's coils (when coils of relay has DC current) or add resistance-capacitance return circuit (when coils of relay has AC current), in order to prevent charge disturbing the controller or others equipment.



#### 15.4 SENSOR INPUT

All oil pressure sensor, auxiliary sensor1, auxiliary sensor2 and auxiliary sensor3 of HMC6000A /HMC6000A 2 series can be configured to current/power/resistance sensor (jumper switch over is as below). Water temperature sensor and oil temperature sensor is fixed resistor sensor.

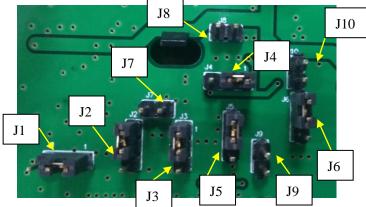


Fig. 8 Sensor Wire Jumper Table 37 Wire Jumper List

Table 57 Wile Sumper List				
Sensors	Jumper Hat	Resistor(Jumper)	Voltage(Jumper)	Current(Jumper)
OP Sensor	J3, J7	Connect to	Connect to J7	Connect to term.2,3
		term.1,2 of J3		of J3
Flexible Sensor1	J4, J8	Connect to	Connect to J8	Connect to 2,3 of
		term.1,2 of J4		J4
Flexible Sensor2	J5, J9	Connect to	Connect to J9	Connect to 2,3 of
		term.1,2 of J5		J5
Flexible Sensor3	J6, J10	Connect to	Connect to J10	Connect to 2,3 of
		term.1,2 of J6		J6
Remark: Water temperature sensor and oil temperature sensor are resistance sensor that cannot be				
changed to others.				

#### 15.5 WITHSTAND VOLTAGE TEST

When controller has been installed in control panel, if need the high voltage test, please disconnect controller's all terminals in order to prevent high voltage into controller and damage it.



# 16 TROBLESHOOTING

# Table 38 Troubleshooting

Problem	Possible Solution		
Controller no response with power.	Check starting batteries; Check controller connection wirings; Check DC fuse.		
Genset shutdown	Check the water/cylinder temperature is too high or not.		
Emergency shutdown	Check emergency shutdown button function.		
Low oil pressure alarm after engine has fired.	Check oil pressure sensor and wiring.		
High water temperature alarm after engine has fired.	Check water temperature sensor and its wiring.		
Shutdown alarm when engine is running	Check relevant switch and its wiring according to the information on LCD;		
	Check auxiliary digital input port.		
	Check fuel return circuit and its wiring;		
Fail to start	Check starting battery;		
	Check speed sensor and its wiring;		
	Consult engine manual.		
Starter no respond	Check starter wiring;		
·	Check start battery.		
	Check wiring;		
	Check if COM port setting is right;		
RS485 communication failure	Check if RS485 A and B wires are connected in the opposite way;		
	Check if PC communication port is damaged;		
	Putting a $120\Omega$ resistance between RS485 A and B is recommended.		
	Check wiring; Check if CANBUS CANH and CANL wires are connected in the		
	opposite way;		
CANBUS communication	Check if CANBUS CANH and CANL wires at both ends are connected		
failure	in the opposite way;		
	Putting a $120\Omega$ resistance between CANBUS CANH and CANL is		
	recommended.		