

MEM40 ENGINE MONITORING CONTROLLER USER MANUAL



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Table 1 Version History

Date	Version	Content
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1 OVERVIEW

MEM40 Engine Monitoring Controller, used for automatic control system of single engine, which can realize engine local/remote start/stop, data measurement, display, alarm protection and etc. With remote monitoring interface, it can connect remote monitoring module and realize engine remote start, stop and other functions.

2 PERFORMANCE AND CHARACTERISTICS

- With 32-bit ARM micro-processor as the core, 4.3-inch LCD display with 240*128 resolution, optional Chinese/English;
- Support J1939 communication interface, dozens of ECU engines monitoring can be realized;
- With one RS485 interface supporting MODBUS RTU communication protocol, can realize remote data communication and "three remote" (remote control, remote measurement, remote communication) functions;
- With local mode and remote mode. Start/stop can be achieved via panel key in local mode and achieved via remote monitoring module in remote mode;
- With remote monitoring interface and can connect remote monitoring module, remote start/stop can be realized in remote mode;
- With override mode, when this mode is active, other alarms without shutdown except for emergency stop and overspeed stop;
- With RPU interface, RPU speed and oil pressure sensor can be connected via it. RPU oil pressure can select resistance/voltage/current type sensor;
- With 4 sensors, 3 of which support resistance/voltage/current type;
- With 2 self-check modes, when this mode is active, it can self-check setting alarm;
- With alarm self-lock function, it will automatically lock after all alarms are triggered. When alarm disappears, only press reset key can remove alarms;
- With alarm log and start/stop event log function, all warning alarm, shutdown alarm and start/stop alarm will be automatically recorded in event log, max recording can reach 200 pieces;
- It can simultaneously display up to 10 SPN alarm contents, and support up to 10 SPN alarm shielding function;
- MEM40-RM module can automatically synchronize MEM40 data and configuration information without setting any parameters, which is simple to use;
- Parameters can be set via panel or connecting PC software through USB(Type-C) interface;
- Digital regulation of all parameters instead of analog regulation using conventional potentiometer, thus improving reliability and stability;
- Metal shell design, compact structure, small size and simple wiring with easy operation.

3 LOCAL AND REMOTE MONITORING CONFIGURATION

Table 2 Configuration List

Item	MEM40	MEM40-RM	Remark
LCD Size/Resolution	4.3" 240*128	4.3" 240*128	
Inputs	7	098333	
Outputs	6	0	
Resistance/Voltage/Current Type	3	0	
Desistence Type Sensors	1	0	
		0	
ECU CANBUS	•		
Remote Monitoring CANBUS	•	•	
RS485	•		
USB (Type-C)	•	•	
	•	•	
Stop Key	•	•	
	•		
Reset Key	•	•	
Mute Key	•	•	
Test Key	•	•	
Local/Remote Key	•		
Brightness		•	
Idle/Rated Button	•		Main engine
Override Mode Button	•	•	Main propulsion
Emergency Stop Button	•	•	

4 TECHNICAL PARAMETERS

Table 3 Technical Parameters

Item	Description		
	DC8V to DC35V, DC reverse connection protection		
Working Voltage	Resolution: 0.1V		
	Accuracy: 1%		
Overall Consumption	<4W (Standby mode: ≤2W)		
	Voltage Range: 1.0V~24.0V (RMS)		
Speed Sensor	Frequency Range: 5Hz~10000Hz		
	Range: DC0V~DC60V		
Charger (D+) Voltage	Resoultion: 0.1V		
	Accuracy: 1%		
	Resistance Input		
	Range: 0Ω~1000Ω		
	Resolution: 0.1Ω		
	Accuracy: 1Ω (below 300Ω)		
	Voltage Input		
	Range: 0V~5V		
Analog Sensor	Resolution: 0.01V		
	Accuracy: 1%		
	Current Input		
	Range: 0mA~20mA		
	Resolution: 0.01mA		
	Accuracy: 1%		
Start Output	16A DC24V supply output (relay output)		
ECU Power	16A DC24V supply output (relay output)		
Digital Output 1	16A DC24V supply output (relay output)		
Digital Output 2	5A DC24V supply output (relay output)		
Digital Output 3	5A DC24V supply output (relay output)		
Digital Output 4	5A DC24V supply output (relay output)		
RS485 Interface	Isolated, half-duplex, 9600 baud rate, no parity, 1/2 stop bit		
	Isolated, 250kbps baud rate. Communication distance is less than or		
ECU CAN Interface	equal to 100m		
	Isolated, defaulted baud rate is 250kbps, which can be set.		
REMOTE CAN Interface	Communication distance is less than or equal to		
	100m(250kbps)/150m(125kbps)		
	5Hz~8Hz: displacement±7.5 mm		
Vibration	8Hz~500Hz: a=4g		
	IEC 60068-2-6		
	50g, 11ms, half-sine, complete shock test from three mutually		
Shock	perpendicular directions, totally 18 times		
	IEC 60068-2-27		
	25g 16ms half-sine		
Bump	IEC 60255-21-2		

Item	Description		
Case Dimension	MEM40: 282mm x 160.5mm x 230mm		
Case Dimension	MEM40RM: 284mm x 227mm x 107mm		
Inatallation	Screw installation		
Working Temperature	(-25~+70)°C		
Working Humidity	(20~93)%RH		
Storage Temperature	(-30~+80)°C		
Protection Level	IP44		
Waight	MEM40: 3.6kg		
weight	MEM40RM: 2.6kg		

5 CONTROLLER INFORMATION DISPLAY

Table 4 Local & Remote Monitoring Information Display

Screen	Display	Description
1 st Screen		It displays engine speed, water temperature, oil
	Engine Data	pressure, RPU speed, oil pressure, power voltage,
	Water Temp 82°C Power 24.5V	charger voltage, start times and accumulated
	0il Press. 325kPa D+: 24.5V	running time. Status line displays current engine
	0il Temp. 80°C Num 3	status and current controller mode
	Run Time: 10.1h	
	At Rest Local Mode	Press (\bullet) or (\bullet) can scroll the screen.
2 nd Screen		It displays engine ECU data, including fuel
	ECU Data	temperature, fuel pressure, inlet temperature,
	Fuel lemp. 45 C Turbo Pressure 310kPa	exhaust temperature fuel consumption total fuel
	Inlet Terre 30°C Coolent Level 80%	consumption Status line displays current engine
	Exhaust Temp 280°C Fuel Consum 15.1L/h	status and current controller mode
	TotalFuelUsed 300L	status and current controller mode.
	At Rest Local Mode	Press 🔺 or 💌 can scroll the screen.
2rd Screen		It displays controller emergency stop status and
5 Screen	Input Status	other inputs status. Input name can automatically
	Emergency Shut. Open	undate according to the definition. Status line
	Fuel Leakage In Open	diambar according to the definition. Status line
	Over Ride Mode Open	displays current engine status and current
		controller mode.
	At Rest Local Mode	Proce A or Y can scrall the screen
4 th Screen	Output Status Ignition Control Close	It displays controller output status. Output name
	Crank Relay Open	can automatically update according to the
		definition. Status line displays current engine
		status and current controller mode.
		-
	At Rest Local Mode	Press \square or \square can scroll the screen.
5 th Screen		The left part of this screen displays controller
	Information	software version, hardware version, release date,
	Soft Ver: 1.2.0.1 Fresh Water Press.	system time. The right part displays data of Aux.
	Release: 2022–10–10 Starting Air Press.	sensor 1, 2, 4. When the sensor is disabled,
	System Time 150kPa	corresponding display will be automatically
	2022-10-10(1)21:27:26 Bearing Temp.	masked.
	At Rest Local Mode	
		Press 📥 or 💌 can scroll the screen.
6 th Screen	Alarm	
	No Alarm	It diaplays controller real time claure information
		Press A or Can scroll the screen

Screen	Display	Description
Event Log		Long press Enter for more than 1s to enter select
	Log[026]	interface to choose event log.
	[001]Event Log 2022-11-07 21:46:2	One screen can display up to 3 log information,
	Local Start [002]Warn Alarm 2022–11–08 22:32:1	display content includes type, name, occur time.
	ECU Warn SPN=110, FMI=0, High	Besides if FCU alarm occurs it will display SPN
	[003]Shutdown 2022-11-09 23:01:1	alarm code of FCU alarm
	0il Pressure Low 85kPa	
		$\blacksquare Press \blacksquare or \blacksquare can scroll the screen.$

6 OPERATION

6.1 PANEL DESCRIPTION



Fig.1 Main Propulsion Monitoring Controller Panel



Fig.2 Main Engine Monitoring Controller Panel



6.2 KEY FUNCTION DESCRIPTION

Table 5 Key Function Description

Key	Function	Description	
0	Stop	Stop running engine in local mode.	
	Start	Start engine in local mode.	
X	Mute	It can remove controller audible alarm.	
	Self-check	Press it can test alarm without speed in standby mode; Please refer to manual detailed description for self-check mode.	
	Reset	Press it to reset alarms when controller has alarm.	
	Up/Increase	 Screen scroll; Up cursor and increase value in setting menu. 	
	Down/Decrease	 Screen scroll; Down cursor and decrease value in setting menu. 	
*/	Local/Remote	Default as local mode when power on. Press it can enter remote mode, meanwhile corresponding indicator will illuminate; press it again can enter local mode, meanwhile corresponding indicator will illuminate.	
¢,	Set/Confirm	1. Press it for more than 1s to enter the parameter setting and controller information selection interface; confirm setting information;	

Key	Function	Description		
		2. After setting, press it can save parameters.		
Ņ	Lamp Test	Press it to enter lamp test mode, screen and panel LED will illuminate.		
Ö.	Dimmer+	Adjust backlight brighter, 6 kinds of lamp brightness levels.		
Ŏ	Dimmer-	Adjust backlight darker, 6 kinds of lamp brightness levels.		
	Override Mode	Only overspeed and emergency stop can make the engine stop in override mode.		
	Idle/Rated	It can control engine speed in local mode while inactive in remote mode.		
	Emergency Stop	When there is emergency situation, press it can disconnect Edignition switch, engine will stop immediately.		
	Power (MEM40RM)	It can control power on/off of remote monitoring module.		

6.3 REMOTE START/STOP OPERATION

6.3.1 ILLUSTRATION

The controller has two remote start/stop methods: input start/stop and start/stop via remote

monitoring module. Firstly, set controller in remote mode via then start/stop through input port or

remote monitoring module can be realized. Turn on the power switch on the side before controller working.

6.3.2 REMOTE START SEQUENCE

- 1) When "Remote Start" is active, "Start Delay" timer is initiated; When it starts via remote monitoring module, it will enter "Preheat" period;
- 2) "Start Delay" countdown will be displayed on LCD;
- 3) When start delay is over, preheat relay energizes (if configured), "Preheat Delay XX s" will be displayed on LCD;
- 4) After the above delay, the Fuel Relay is energized, and then one second later, the Start Relay is engaged. If the engine fails to fire during this cranking attempt then the fuel relay and start relay are disengaged for the pre-set rest period; "Crank Rest Time" begins and wait for the next crank attempt;
- Should this start sequence continue beyond the set number of attempts, the start sequence will be terminated, the first line of LCD display will be highlighted with black and 'Fail to Start fault' will be displayed;
- 6) In case of successful crank attempt, the "Safety On" timer is activated. As soon as this delay is over, "Start Idle" delay is initiated (if configured);
- 7) After the start idle, it will enter "High-speed Warming Up" (if configured);
- 8) When the delay is over, engine will run normally.

6.3.3 REMOTE STOP SEQUENCE

- 1) When "Stop Input" is effective, the Stop Delay is initiated. When it stops via remote monitoring module, it will enter "High-speed Cooling" period directly;
- 2) When stop delay is over, "High-speed Cooling" begins;
- 3) Once this delay has expired, "Stop Idle" is initiated (if configured), idle relay is energized;
- 4) Once this "Stop Idle" has expired, the "ETS Solenoid Hold" begins. ETS relay is energized while ignition relay and fuel relay are de-energized;
- 5) Once this "ETS Solenoid Hold" has expired, "Fail to Stop Delay" begins. Complete stop is detected automatically;
- 6) Engine is placed into its standby mode after its complete stop. Otherwise, fail to stop alarm is initiated (If engine stops successfully after "fail to stop" alarm is initiated, it will enter standby mode).

6.4 LOCAL START/STOP OPERATION

6.4.1 ILLUSTRATION

Switch to local mode through panel key, then start/stop operation is enabled.

6.4.2 LOCAL START SEQUENCE

- 1) Press **L**, preheat relay is energized (if configured), "Preheat XX" will be displayed on LCD;
- After preheat delay is over, Fuel Relay is energized, and then one second later, the Start Relay is engaged. If the engine fails to fire during this cranking attempt then the fuel relay and start relay are disengaged for the pre-set rest period; "ETS Solenoid Hold" begins;
- 3) In case of successful crank attempt, the "Safety On" timer is activated;
- 4) After the delay is over, if controller speed, water temperature and oil pressure are normal, controller will directly enter "Normal Running".

6.4.3 LOCAL STOP SEQUENCE

- 1) Press O, "ETS Solenoid Hold" is energized, ETS relay is engaged, ignition relay and fuel relay are disengaged;
- 2) After ETS delay is over, "Fail to Stop Delay" begins. Complete stop is detected automatically.
- 3) Engine is placed into its standby mode after its complete stop. Otherwise, fail to stop alarm is initiated (If engine stops successfully after "fail to stop" alarm is initiated, it will enter standby mode).

Mode	Key Start	Key Stop	Remote Start	Remote Stop	MEM40RM Start	MEM40RM Stop
Local	•	•	-	-	-	-
Remote	_	_	•	٠	•	•

Table 6 MEM40 Start/stop Illustration

7 ALARM

7.1 WARNING ALARM

When controller detects warning signal, it only issues warning without shutdown and displays alarm type.

No.	Warning	Detect Range	Description
1.	Overspeed	Always active	When controller detects engine speed is greater than threshold, it will send warning signal, corresponding information will be displayed on the LCD.
2.	Underspeed	Warming up → Stop cooling	When controller detects engine speed is lower than threshold, it will send warning signal, corresponding information will be displayed on the LCD.
3.	Speed Signal Loss	Start idle delay→ Stop idle	When controller detects engine speed is 0 and speed signal loss warning is enabled, it will send warning signal, corresponding information will be displayed on the LCD.
4.	Speed Break Wire	Always active	When controller detects engine speed sensor wire is broken, it will send warning signal, corresponding information will be displayed on the LCD.
5.	Start Failure	After starting in set crank attempt	If engine fails to fire in set crank attempt, controller will send warning signal, corresponding information will be displayed on the LCD. NOTE: In local mode, start attempt only has once and no alarm for start failure.
6.	Stop Failure	After engine complete stop delay	When engine complete stop delay is over, if there is speed signal, controller will send warning signal, corresponding information will be displayed on the LCD.
7.	Charging Failure	From engine normal running	When controller detects charger voltage is lower than threshold, it will send warning signal, corresponding information will be displayed on the LCD.
8.	Aux. Input 1-6	User-defined active range	When controller detects Au.x input 2-6 warning input is active, it will send warning signal, corresponding information will be displayed on the LCD.
9.	High Water Temp	Exceed set speed	When controller detects high water temperature warning is active, it will send warning signal, corresponding information will be displayed on the LCD.
10.	High Oil Temp	Exceed set speed	When controller detects high oil temperature warning is active, it will send warning signal, corresponding information will be displayed on the LCD.
11.	Low Oil Pressure	Exceed set speed	When controller detects low oil pressure warning is active, it will send warning signal, corresponding information will be displayed on the LCD.

Table 7 Warning Alarm

No.	Warning	Detect Range	Description
12.	Aux. Sensor 1-4 High	Exceed set speed	When controller detects Aux. sensor 1-4 warning is active, it will send warning signal, corresponding information will be displayed on the LCD.
13.	Aux. Sensor 1-4 Low	Exceed set speed	When controller detects sensor 1-4 warning is active, it will send warning signal, corresponding information will be displayed on the LCD according to user-defined function selection.
14.	Aux. Sensor 1-4 Open	Always active	When controller detects sensor warning is active, it will send warning signal, corresponding information will be displayed on the LCD according to user-defined function selection.
15.	Power Undervoltage	Always active	When controller detects power voltage is lower than threshold and continues for more than 20s, it will send warning signal, corresponding information will be displayed on the LCD.
16.	Power Overvoltage	Always active	When controller detects power voltage is greater than threshold, it will send warning signal, corresponding information will be displayed on the LCD.
17.	MEM40RM Comm. Failure	Always active (detect after module is enabled)	When controller detects communication failure with remote monitoring module, controller will send warning signal, corresponding information will be displayed on the LCD.
18.	Fuel Leakage	Always active	When this input is active, controller will send warning signal, corresponding information will be displayed on the LCD.
19.	ECU Warn	Always active	When there is ECU warning, controller will display "ECU Warning" information, meanwhile SPN and FMI of ECU alarm will be displayed. It can display 10 SPN code of ECU alarm at most.
	7		

7.2 SHUTDOWN ALARM

When controller detects shutdown signal, it will shut down and display alarm type.

Table 8 Shutdown Alarm

No.	Shutdown	Detect Range	Description
1.	Emergency Stop	Always active	When controller detects emergency stop is active, it will send shutdown alarm signal, corresponding
2.	Overspeed Shut.	Always active	information will be displayed on the LCD. When controller detects engine speed is greater than threshold, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
3.	RPU Overspeed	Always active	When controller detects engine RPU speed is greater than threshold, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
4.	Aux. Input 1-6 Shut	User-defined active range	When controller detects Aux. input 1-6 input is active, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
5.	High Water Temp.	Exceed set speed	When controller detects high water temperature shutdown is active, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
6.	High Oil Temp.	Exceed set speed	When controller detects high oil temperature shutdown is active, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
7.	Low Oil Pressure	Exceed set speed	When controller detects low oil pressure shutdown is active, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
8.	High Water Temp. IN	Always active	When controller detects high water temperature shutdown input is active, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
9.	High Oil Temp. IN	Always active	When controller detects high oil temperature shutdown input is active, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
10.	Low Oil Pressure IN	Start idle ~ Stop idle	When controller detects low oil pressure shutdown input is active, it will send shutdown alarm signal, corresponding information will be displayed on the LCD.
11.	Aux. Sensor 1-4 High	Exceed set speed	When controller detects Aux. sensor 1-4 shutdown input is active, it will send shutdown alarm signal,

No.	Shutdown	Detect Range	Description
			corresponding information will be displayed on the
			LCD according to user-defined function selection.
			When controller detects sensor 1-4 shutdown is active,
12	Aux. Sensor 1-4 Low	Exceed set speed	it will send shutdown alarm signal, corresponding
12.			information will be displayed on the LCD according to
			user-defined function selection.
			When there is ECU shutdown, controller will display
No. 12. / 13. Е	FOLL Chutdown	Always active	"ECU Shutdown" information, meanwhile SPN and FMI
15.			of ECU alarm will be displayed. It can display 10 SPN
			code of ECU alarm at most.
	TE: Shutdown type of a	uxiliary inputs must be c	onfigured by users for active.

Ge

ANOTE: Aux. sensor 1~4 must be configured by users for active.

8 PARAMETER SETTING

Long press 🚧 for 1s to enter parameter setting and event log select screen after the controller is

powered on. Correct password is necessary for parameter setting, default password is 00318.

When the password if forgotten or sensor resistance/current calibration is required, please contact the factory.

	ltem	Range	Defaults	Remark
1	Start Delay	(1-3600)s	1	Time from remote start signal is active to start when controller in remote mode.
2	Stop Delay	(1-3600)s	1	Time from remote stop signal is active to stop when controller in remote mode.
3	Preheat Time	(0-3600)s	0	Power-on time of preheating device before starter is powered on.
4	Crank Time	(3-60)s	8	Time for each starter power-on time.
5	Crank Rest	(3-60)s	10	It is the waiting time before second power on when engine fails to start.
6	Safety On Time	(0-3600)s	10	Running time after cranking disconnect.
7	Start Idle Time	(0-3600)s	0	Genset idle running time when starting.
8	High-speed Warming Up	(0-3600)s	10	Genset high-sped warming up time.
9	High-speed Cooling Time	(0-3600)s	10	High-speed cooling time before stopping.
10	Stop Idle Time	(0-3600)s	0	Genset stop idle running time when stopping.
11	ETS Time	(0-3600)s	20	Stop electromagnet power-on time in stopping.
12	After Stop Time	(0-3600)s	0	When "ETS Hold Time" is 0, it is the time from idle delay end to after stop time; when "ETD Hold Time" is not 0, it is the time from ETS delay end to after stop time.
13	Start Key Confirm Delay	(0.2-5.0)s	0.2	When controller starts via key, it is the time from pressing start key to start.
14	Stop Key Confirm Delay	(0.2-5.0)s	0.2	When controller stops via key, it is the time from pressing stop key to stop.
15	Engine Type	(0-39)	1: Common J1939	Select corresponding type according to engine model.
16	SPN Alarm Version	(1-3)	1	SPN alarm parsing type.
17	ECU Shutdown	(0-1)	0: Disable	After it is enabled, it will shut down

Table 9 Parameter Setting Item

ltem		Range Defaults		Remark	
				when engine detects red light alarm.	
18	Flyweel Teeth	(1-300)	118	Flywheel teeth installed on the engine, which is used for judging starter disconnect conditions and detecting engine speed, refer to following installation description. (Using for corresponding RPU speed computing.)	
19	Rated Speed	(1-5999)r/min	1500	Provide standard for over/under speed judging.	
20 (Crank Attempt	(1-30)	3	Max. crank time. When it reaches set attempt, controller will send crank failure signal.	
21 (Crank Disconnect Condition	(0-2) 0: Speed 1: OP 2: Speed + OP	0: Speed	There are 3 conditions for starter and engine disconnect, which can be used separately or together, aiming to disconnect starter motor and engine as soon as possible.	
22 (Crank Disconnect OP	(10-1000)kPa	80	When oil pressure is greater than set value, starter will disconnect.	
23	Crank Disconnect Speed	(0-200)%	25%	Set value is the percentage of rated speed, when speed exceeds it, starter will disconnect.	
24 (Overspeed Shutdown	(0-1) 0 Disable 1 Enable	1 Enable	Overspeed shutdown setting.	
25	Threshold (Shutdown)	(0-200)%	115%		
26 \$	Shutdown Delay	(0-3600)s	1		
27	Overspeed Warning	(0-1) 0 Disable 1 Enable	1 Enable	Oversped warning setting.	
28	Threshold (Warning)	(0-200)%	110%		
29 \	Warning Delay	(0-3600)s	3		
30	RPU Overspeed Shut	(0-1) 0 Disable 1 Enable	1 Enable	RPU sopeed shutdown.	
31	RPU Threshold (Shut)	(0-200)%	115%		
32	RPU Shutdown Delay	(0-3600)s	1		
33 3	Speed Signal Loss	(0-3600)s	3	Time from detecting speed is 0 to confirm action.	
34	Loss Action	(0-2) 0: Warning 1: Shutdown 2: No Action	0: Warning	Controller	
35 (Charging Failure Warning	(0-60.0)V	16.0	After engine is normally running, if charger voltage is lower than it,	

Item	Range	Defaults	Remark	
			controller will send charging failure	
			warning.	
36 Power Rated Voltage	(0-60 0)V	24.0	Provide standard for battery	
	(0 00.0) V	24.0	over/under voltage.	
37 Power Overvoltage	(0-200)%	125%	Set value is the percentage of	
38 Power Undervoltage	(0-200)%	75%		
39 Heating Upper Limit	(0-100) ℃	42	Disconnect when water temperature	
		12	sensor value is greater than set value.	
40 Heating Lower Limit	(0-100) ℃	37	Closewhen water temperature sensor	
	(value is lower than set value.	
41 Speed Wire Break	(0-1)0 Disable 1	0 Disable	After it is enabled, it can detect wire	
	Enable		break of engine speed sensor.	
42 Equipment Address	(1-254)	1	RS485 communication address.	
	(0-1)			
43 Language	0: Simplified	0: Simplified	Controller displays language selection.	
	Chinese	Chinese		
	1: English			
44 Password	(0-65535)	00318	Password for entering parameter	
45 MEM40RM Enable	(0-1)	0 Disable	If MEM40RM is required, it should be	
	(0.1)		enabled.	
46 Doud Data	(0-1)	0: 250khpa	Communication baud rate of remote	
40 Dauu Rale	0. 250kbps	0. 250kbps	monitoring module CANBUS port.	
			When self-sheek mode is 1 it can	
	(0-1)		connect corresponding sensor to	
	0: Self-check		detect alarm without speed after	
47 Self-check Mode	Mode 1	0: Self-check	self-check is active	
47 Och oneok would	1 [°] Self-check	Mode 1	When self-check mode is 2 system	
	Mode 2		will automatically change sensor data	
			to test alarm after self-check is active.	
48 Date and Time			Controller time setting.	
49 Water Temp. Sensor				
(ECU Data Input)	Details see 9.3.		Water temperature sensor setting.	
50 Oil Temp. Sensor (ECU				
Data Input)	Details see 9.3.		Oil temperature sensor setting.	
51 OP Sensor (ECU Data				
Input)	Details see 9.3.		Oil pressure sensor setting.	
52 Aux. Sensor 1 Set	Details see 9.3.			
(Resistance/Voltage/	(Resistance/Voltage/ NOTE: Resistance/voltage in		Aux. sensor 1 setting.	
Current Input)	inactive.)			
53 Aux. Sensor 2 Set	Details see 9.3.			
(Resistance/Voltage/	NOTE: Resistance/v	oltage input is	Aux. sensor 2 setting.	
Current Input)	inactive.)			

	Item	Range	Defaults	Remark
54	Aux. Sensor 3 Set	Details see 9.3.		Aux concer 2 potting
	(Resistance/Voltage/	NOTE: Resistanc	e/voltage input is	Aux. sensor 5 setting.
	Current Input)	inactive.)		Default as RPU oil pressure sensor.
55	Aux. Sensor 4 Set (Resistance Input)	Details see 9.3.		Aux. sensor 4 setting.
56	Input 1 Configuration	(0-50)	4: Idle/High Speed Input	See 9.1.2.
57	Input 1 Active Type	(0-1)	0: Closed for Active	Set input port as closed or opened.
58	Input 2 Configuration	(0-50)	11: Fuel Leakage	See 9.1.2.
59	Input 2 Active Type	(0-1)	0: Closed for Active	Set input port as closed or opened.
60	Input 3 Configuration	(0-50)	8: Not Used	See 9.1.2.
61	Input 3 Active Type	(0-1)	0: Closed for Active	Set input port as closed or opened.
62	Input 4 Configuration	(0-50)	0: Not Used	See 9.1.2.
63	Input 4 Active Type	(0-1)	0: Closed for Active	Set input port as closed or opened.
64	Input 5 Configuration	(0-50)	0: Not Used	See 9.1.2.
65	Input 5 Active Type	(0-1)	0: Closed for Active	Set input port as closed or opened.
66	Input 6 Configuration	(0-50)	0: Not Used	See 9.1.2.
67	Input 6 Active Type	(0-1)	0: Closed for Active	Set input port as closed or opened.
68	Output 1 Configuration	(0-100)	1: Start Output	See 9.2.2.
69	Output 1 Active Type	(0-1)	0: Normally Open	Set output port as normally closed or opened.
70	Output 2 Configuration	(0-100)	7: Ignition Control	See 9.2.2.
71	Output 2 Active Type	(0-1)	0: Normally Open	Set output port as normally closed or opened.
72	Output 3 Configuration	(0-100)	0: Not Used	See 9.2.2.
73	Output 3 Active Type	(0-1)	0: Normally Open	Set output port as normally closed or opened.
74	Output 4 Configuration	(0-100)	0: Not Used	See 9.2.2.
	от	(0,1)	0: Normally	Set output port as normally closed or
/5	Output 4 Active Type	(0-1)	Open	opened.
76	Output 5 Configuration	(0-100)	0: Not Used	See 9.2.2.
77	Output 5 Active Type	(0-1)	0: Normally Open	Set output port as normally closed or opened
78	Output 6 Configuration	(0-100)	0: Not Used	See 9.2.2
	calput o configuration		0: Normally	Set output nort as normally closed or
79	Output 6 Active Type	(0-1)	Open	opened.

9 INPUT PORT & OUTPUT PORT DEFINITION

9.1 AUXILIARY INPUT PORT 1-6 FUNCTION DEFINITION

9.1.1 DEFINED CONTENTS OF DIGITAL INPUT PORT

Table 10 Defined Contents of Digital Input Port

No.	ltem	Contents	Description
1	Input Port Function Setting	(0- 50)	See 9.1.2 Input Port Function Definition.
2	Input Port Active Type	(0-1)	0: Closed 1: Opened
3	Input Port Active Range	(0-3)	0: From Safety On 1: From Cranking 2: Always 3: Inactive
4	Input Port Active Action	(0-2)	0: Warning 1: Shutdown 2: Indication
5	Input Delay	(0-20.0)s	
6	Display Character String	Custom input port name	20 English characters or 10 Chinese.characters

9.1.2 INPUT PORT FUNCTION DEFINITION

Table 11 Input Port Function Definition

No.	ltem	Description
0.	Not Used	Not used.
1.	User-defined	Input port content can be defined.
2	Alorm Muto	"Audible Alarm" in output configuration can be prohibited when
Ζ.	Aldini Mute	it is active.
3.	Alarm Reset	Reset all alarms when it is active.
1	A Demote Emergency Step	When it is active, controller will send stop command and display
4.	Remote Linergency Stop	"Remote Emergency Stop" on the LCD.
5.	Reserved	
6.	Reserved	
7.	Reserved	
8.	Reserved	
		Engine will not automatically enter high speed mode after
٥	Idle/High Speed	cranking under local mode. Only when controller sends high
9.	idie/Tilgii Speed	speed command after idle/high speed signal is active can
		engine enters high speed running.
10.	Barring Gear Interlock	Engine is prohibited to start after it is active.
11.	Fuel Leakage	Fuel leakage alarm occurs when it is active.
12.	Reserved	
13.	Reserved	
14.	Reserved	

No.	ltem	Description
		Connects sensor digital input. When it is active, controller will
15.	High Water Temp. Shut	send stop command and display corresponding information on
		the LCD.
16.	Reserved	
		Connects sensor digital input. When it is active, controller will
17.	Low Oil Pressure Shut.	send stop command and display corresponding information on
		the LCD.
18.	Local Mode	System enters local mode when it is active.
19.	Remote Mode	System enters remote mode when it is active.
00	Domoto Stort	When it is active in remote mode, controller will send start
20.	Remote Start	command.
01	Domoto Ston	When it is active in remote mode, controller will send stop
Ζ١.	Remote Stop	command.
		In remote mode, when it is active, controller will start while stop
22.	Remote Start/Stop	when it is inactive. It can't be used simultaneously with remote
		start and remote stop.
22	Override Mede	When it is active, shutdown alarms are disabled except for
Ζ3.	Override Mode	overspeed shutdown and emergency stop.
24.~ 50.	Reserved	

NOTE: The defined name of input port 1-6 only can be configured via computer software.

9.2 OUTPUT PORT DEFINITION

9.2.1 DEFINED CONTENTS OF DIGITAL OUTPUT PORT

Table	12	Defined	d Co	ntents	of	Digital	Output Port

No.	Item	Content	Remark
1	Function Configuration	(0-100)	
2	Active Method	0 Normally Open 1 Normally Close	
		Bit1: At Rest	
		Bit2: Preheat	
		Bit3: Fuel Output	
		Bit4: Cranking	
		Bit5: Crank Rest	
		Bit6: Safety On	
		Bit7: Start Idle	
3	Active Period	Bit8: Warming Up	
		Bit9: Wait for Load	
		Bit10: Normal Running	
		Bit11: Cooling Down	
		Bit12: Stop Idle	
		Bit13: ETS Hold	
		Bit14: Wait Stop	
		Bit15: Stop Failure	
5	Delay Output Timne	(0-100.0)S	
6	Continuous Output Time	(0-3600)S	

9.2.2 FUNCTION DEFINITION OF OUTPUT PORT 1-6

Table 13 Function Definition of Output Port 1-6

No.	Item	Description		
0.	Not Used	It is not used.		
1.	User-defined	See table 12.		
2.	Air Flap Control	It can close the air flap in overspeed alarm shutdown and emergency stop.		
3.	Audible Alarm	Action in warning and shutdown. It can externally connect the announciator. When "Alarm Mute" is active, it can't output.		
4.	Crank Relay	It is active in generator cranks and inactive after crank disconnect.		
5.	Fuel Relay	It is active in generator starts and inactive in waitinf for stop.		
6.	ETS Output	Action in ETS delay.		
7.	ECU Power	ECU power output end. When the monitoring controller is powered on, it will output and deactivate in power off.		
8.	Ignition Control	ECU ignition control. It will output in power on and deactivate in stop.		
9.	Loss of Speed Signal	Action when speed is 0 after safety on.		
10.	Reserved			
11.	Override Mode	Output when it is in override mode.		
12.	Standby Engine (1)	Output when controller in standby status and no sensor open alarm. It is only active in remote mode.		
13.	Heating Control	It is controlled by heating upper and lower limit of temperature sensor.		
14.	Idle Control	Action in crank-start idle and stop idle-wait for stop. It is inactive in local mode.		
15.	Common Alarm	Action in common warning, common shutdown alarm occurs.		
16.	Common Shutdown Alarm	Action in common shutdown alarm occurs.		
17.	Common Warning Alarm	Action in common warning alarm occurs.		
18.	Input 1 Active	Action in digital input 1 is active.		
19.	Input 2 Active	Action in digital input 2 is active.		
20.	Input 3 Active	Action in digital input 3 is active.		
21.	Input 4 Active	Action in digital input 4 is active.		
22.	Input 5 Active	Action in digital input 5 is active.		
23.	Input 6 Active	Action in digital input 6 is active.		
24.	Crank Sucess	It is active when engine speed is greater than 500rpm and inactive when it is lower than 100rpm.		
25.	Normal Running	It is active when engine speed is greater than 85% of rated speed and inactive when it is lower than 75%.		
26.	Remote Mode	Output when controller in remote mode		
27.	Local Mode	Output when controller in local mode		
28.	Standby Engine (2)	Output when there is no shutdown alarm, it is only active in remote mode.		

No.	ltem	Description
29.	Reserved	
30.	Stop Status	Output when controller in standy status.
21	Power Underveltage	Output when controller detects power voltage is lower than set
51.	Power ondervoltage	value.
32	Power Overvoltage	Output when controller detects power voltage is greater than
52.	1 Ower Overvoltage	set value.
33.	Reserved	
34.	Reserved	
35.	Overspeed Warning	Action in engine overspeed warning occurs.
36.	Oversped Shutdown	Action in engine overspeed shutdown alarm occurs.
37.	Emergency Stop Alarm	Action in emergency stop alarm occurs.
38.	Charging Failure	Action in charging failure alarm occurs.
39.	Start Failure Alarm	Action in start failure alarm occurs.
40.	Stop Failure Alarm	Action in stop failure alarm occurs.
41.	Reserved	
42.	Reserved	
43.	High Water Temp. Warn	Action in high water temperature warning occurs.
44.	High Water Temp. Shut.	Action in high water temperature shutdown occurs.
45.	Reserved	
46.	High Oil Temp. Warn	Action in high oil temperature warning occurs.
47.	High Oil Temp. Shut.	Action in high oil temperature shutdown occurs.
48.	Reserved	
49.	Low OP Warn	Action in low oil pressure warning occurs.
50.	Low OP Shut.	Action in low oil pressure shutdown occurs.
51.	Aux. Sensor 1 Open	Action in Aux. sensor 1 open alarm occurs.
52.	Aux. Sensor 1 Warn	Action in Aux. sensor 1 warning alarm occurs.
53.	Aux. Sensor 1 Shut	Action in Aux. sensor 1 shutdown alarm occurs.
54.	Aux. Sensor 2 Open	Action in Aux. sensor 2 open alarm occurs.
55.	Aux. Sensor 2 Warn	Action in Aux. sensor 2 warning alarm occurs.
56.	Aux. Sensor 2 Shut	Action in Aux. sensor 2 shutdown alarm occurs.
57.	Aux. Sensor 3 Open	Action in Aux. sensor 3 open alarm occurs.
58.	Aux. Sensor 3 Warn	Action in Aux. sensor 3 warning alarm occurs.
59.	Aux. Sensor 3 Shut	Action in Aux. sensor 3 shutdown alarm occurs.
60.	Reserved	
61.	Oil Pre-supply Output	Output in crank-safety on.
62.	Fuel Pre-supply Output	Output in preheat-safety on.
63.	Aux. Sensor 4 Open	Action in Aux. sensor 4 open alarm occurs.
64.	Aux. Sensor 4 Warn	Action in Aux. sensor 4 warning alarm occurs.
65.	Aux. Sensor 4 Shut	Action in Aux. sensor 4 shutdown alarm occurs.
66.	Fuel Leak Alarm	Output in fuel leak alarm occurs.
67.	Reserved	
68.	Reserved	
69.	Lamp Test	Output in lamp testing.
70.	Overspeed Shutdown	Output in RPU overspeed shutdown ocurs.

No.	Item	Description
	(RPU)	
71.	Remote Emergency Stop	Output in remote emergency stop occurs.
72.	Reserved	
73.	Reserved	
74.	Reserved	
75.	Alarm Blink	Output when monitoring controller detects alarm. When there is alarm again, this output port will deactivate for 2s and continue to output continuously.
76~100	Reserved	Reserved.

9.3 SENSOR FUNCTION DEFINITION

9.3.1 SENSOR CUSTOM LIST

Table 14 Sensor Custom List

No.	ltem	Content	Remark
1.	Sensor Type	(0-3) 0: Not Used 1: Pressure Sensor 2: Temp. Sensor 3: Level Sensor	Water temperature, oil temperature, oil pressure sensor types are not selected, data is read by ECU.
2.	Sensor Curve	Sensor type list	See 9.3.2/9.3.3/9.3.4 curve list (water temperature, oil temperature, oil pressure data is read by ECU, so curve is not selected.)
3.	Alarm Speed	(0-200)%	Detect when speed is greater than it.
4.	Range	(0-6000)	It is active in (4~20)mA sensor. Pressure sensor nit is kPa Level sensor unit is % (water temperature, oil temperature, oil pressure data is read by ECU, so there is no this item)
5.	Display Unit	Temperature 0: °C 1: °F Pressure 0: kPa 1: bar 2: psi Level unit is fixed as "%"	Displayed unit on the controller interface, displayed data will be automatically converted after selecting unit.
6.	Sensor High Shutdown	(0-1) 0: Enable 1: Disable	
7.	Set Value	(0-6000)	
8.	Delay	(0-3600)s	

No.	ltem	Content		Remark
		(0-1)		
9.	Sensor Low Shutdown	0: Enable		
		1: Disable		
10.	Set Value	(0-4000)		
11.	Delay	(0-3600)s		
		(0-1)		
12.	Sensor High Warning	0: Enable		
		1: Disable		
13.	Set Value	(0-6000)		
14.	Delay	(0-3600)s		
		(0-1)		
15.	Sensor Low Shutdown	0: Enable		
		1: Disable		
16.	Set Value	(0-4000)		
17.	Delay	(0-3600)s		
10	1st point V (Posistance)	Resistance	type	
10.		(non-PT100)		
10	2 nd Doint V (Desistance)	Resistance	type	
19.		(non-PT100)		
20	2rd Daint V (Dagistance)	Resistance	type	
20.	3 rd Politi X (Resistance)	(non-PT100)		
21	(th Deint V (Decistered)	Resistance	type	
21.		(non-PT100)		
22	5 th Doint V (Decistance)	Resistance	type	
22.	J [®] Point X (Resistance)	(non-PT100)		
22	6 th Doint V (Popietanoo)	Resistance	type	
23.		(non-PT100)		
24	7 th Point X (Pesistance)	Resistance	type	Customer can define sensor curve, X-axis
24.		(non-PT100)		is 8 points, Y-axis is 8 points. (water
25	8 th Point X (Resistance)	Resistance	type	temperature, oil temperature, oil pressure
20.		(non-PT100)		data is read by ECU, so there is no this
26	1 st point V (Value)	Resistance	type	item)
20.		(non-PT100)		
27	2 nd Doint V (Value)	Resistance	type	
27.		(non-PT100)		
28	3rd Doint V (Value)	Resistance	type	
20.	5 Follit F (Value)	(non-PT100)		
20	A th Doint V (Value)	Resistance	type	
29.		(non-PT100)		
30	5 th Point V (Value)	Resistance	type	
50.		(non-PT100)		
21	6 th Point V (Value)	Resistance	type	
51.		(non-PT100)		
32.	7 th Point Y (Value)	Resistance	type	

No.	Item	Content	Remark	
		(non-PT100)		
22	9th Doint V (Value)	Resistance type		
33.		(non-PT100)		
24	Custom Character	User can define sensor	It only can be set through upper computer	
34.	String	name	software.	

9.3.2 TEMPERATURE CURVE LIST

Table 15 Temperature Curve List

No.	ltem	Remark
0	Not Used	
1	PT100	
2	Custom Resistance Curve	
3	VDO	
4	CURTIS	
5	VOLVO-EC	
6	DATCON	
7	SGX	Desistance range of evictory register as type input is (0,1000)0
8	SGD	Resistance range of custom resistance type input is $(0-1000)\Omega$.
9	SGH	
10	Reserved	
11	Cu50	
12	Reserved	
13	Reserved	
14	Reserved	
15	Reserved	

NOTE: The division value of PT100 resistance type temperature sensor is fixed as 0.385 (0.385Ωcorresponds to 1°C).

9.3.3 PRESSURE CURVE LIST

Table 16 Pressure Curve List

No.	Item	Remark
0	Not Used	
1	(4~20)mA	
2	Custom Resistance Curve	
3	VDO 10bar	
4	CURTIS	
5	Voltage Type (0.5V-4.5V)	
6	DATCON 10bar	
7	SGX	Desistance range of sustam resistance type input is (0, 1000)0
8	SGD	Resistance range of custom resistance type input is $(0-1000)\Omega$.
9	SGH	
10	Voltage Custom Curve	
11	Reserved	
12	Reserved	
13	Reserved	
14	Reserved	
15	Reserved	

NOTE: If pressure signal is current type, no need for setting curve but for range.

9.3.4 LEVEL CURVE LIST

Table 17 Level Curve List

No.	ltem	Remark
0	Not Used	
1	(4~20)mA	
2	Custom Resistance Curve	
3	SGD	
4	SGH	
5	Reserved	
6	Reserved	
7	Reserved	Projectore range of suptom resistance type input is (0.1000)
8	Reserved	Resistance range of custom resistance type input is $(0-1000)\Omega$.
9	Reserved	
10	Reserved	
11	Reserved	
12	Reserved	
13	Reserved	
14	Reserved	
15	Reserved	

NOTE: If pressure signal is current type, no need for setting curve but for range.

10 PARAMETER SETTING

10.1 CONFIGURATION CAUTION

Long press in for 1s can enter parameter setting and controller information selection interface

after controller is powered on. Correct password is required for parameter setting, which is defaulted as 00318.

If the password is forgotten or sensor resistance/voltage/current calibration is necessary, please contact the factory.

- Please modify controller internal parameters (crank disconnect conditions seletion, Aux. input, output configuration, various delay, etc.) in standby status, otherwise shutdown alarm or other abnormal situations may occur.
- Sensor high alarm threshold must be greater than low alarm threshold, otherwise alarm may occur simultaneously.
- Overspeed threshold must be greater than underspeed threshold, otherwise overspeed and underspeed may occur simultaneously.
- When setting crank disconnect conditions, engine crank disconnect speed threshold should be set as lower value as soon as possible, so as to disconnect starter quickly.
- Aux. input port can't be set as same item, otherwise function may have fault; Aux. output port can be set as same item.

10.2 SENSOR SETTING

- When reselect sensor, the standard value of the selected sensor curve is called. If defaulted temperature sensor is PT100, then sensor curve is PT100 curve; if selected as SGD (120°C resistance type), temperature sensor curve is SGD curve.
- If there is difference between standard sensor curve and used sensor, "custom sensor" can be selected, then enter custom sensor curve.
- When enter sensor curve, X value (resistance type) must beentered in descending order, otherwise an error will occur.
- The ordinates of the first or last points can be set same, as shown in the figure below:







	N/m² (Pa)	kgf/cm ²	bar	psi
1Pa	1	1.02x10 ⁻⁵	1x10 ⁻⁵	$1.45 \text{x} 10^{-4}$
1kgf/cm ²	9.8x10 ⁴	1	0.98	14.2
1bar	1x10 ⁵	1.02	1	14.5
1psi	6.89x10 ³	7.03x10 ⁻²	6.89x10 ⁻²	1

11 MEM40 SYSTEM APPLICATION AND INTERFACE DESCRIPTION

11.1 MEM40 SYSTEM APPLICATION DIAGRAM



Fig.5 MEM40 System Application Diagram

11.2 MEM40 INTERFACE

11.2.1 MEM40 SIDE PANEL DIAGRAM



Fig.6 MEM40 Side Panel Diagram

11.2.2 INTERFACE PARAMETER

Table 19 Interface Parameter

Parameter	RM Interface	RPU Interface	Control Interface
Number	7	7	23
Rated Current (A)	10	5	8
Diameter (mm)	1.5	1	1.3
Working Voltage (AC.V)	500	400	250
Withstand Voltage (AC.V)	1500	1200	1000
Contact Resistance (M Ω)	5	5	Max 20
Insulation Resistance ($M\Omega$)	>=1000	2000	>=100
Wire Gauge (mm ²)	1.0	0.75	1.0

11.2.3 INTERFACE DIMENSION DIAGRAM



Fig.7 Remote Monitoring Interface Dimension Diagram





Fig.8 RPU Interface Dimension Diagram





11.3 MEM40 INTERNAL WIRING DIAGRAM



Fig.10 MEM40 Internal Wiring Diagram

ANOTE: MEM40-B is internal master control panel, P1~P8 are terminal block number.

11.4 RPU INTERFACE DESCRIPTION

RPU interface is shown as the following:



Pin	1	2	3	4	5	6	7
Definition	RS485A	RS485B	RPU OP VCC	RPU OP GND	RPU OP OUT	RPU SPEED A	RPU SPEED B

Fig.11 RPU Interface

Table 20 RPU Interface Definition

Pin	Definition	Size	Description			
1	RS485(A)	0.5mm ²	It is used for remote centralized monitoring, supporting			
2	RS485(B)	0.5mm ²	Modbus-RTU communication protocol.			
3	RPU OP VCC	0.5mm ²	RPU oil pressure sensor supplies power, output 5V.			
4	RPU OP GND	0.5mm ²	RPU oil pressure sensor common terminal.			
5	RPU OP OUT	0.5mm ²	RPU oil pressure sensor voltage signal input.			
6	RPU SPEED A	0.5mm ²	Connect positive terminal of RPU speed sensor.			
7	RPU SPEED B	0.5mm ²	Connect negative terminal of RPU speed sensor.			

11.5 REMOTE MONITORING INTERFACE DESCRIPTION

RPU interface is shown as the following:

Remote Monitoring Interface



Pin	1	2	3	4	5	6	7
Definition	POWER+	POWER-	NC	Emergency Stop	CANL	CANH	NC

Fig.12 Remote Monitoring Interface

Table 21 Remote Monitoring Interface Definition

Pin	Definition	Size	Description
1	Power+	1.0mm ²	Remote monitoring power B+.
2	Power-	1.0mm ²	Remote monitoring power B
3	NC		Backup.
4	Emergency Stop	0.5mm ²	Remote emergency stop input.
5	CANL	0.5mm ²	It is used for connecting remote monitoring module, 120Ω
6	CANH	0.5mm ²	has been internally installed between CANH and CANL.
7	NC		Backup

11.6 CONTROL INTERFACE DESCRIPTION

Control interface is shown as the following:

Control Interface



Bac	1 :kup	2 Pov	2 ver+	Sta	3 art+	ء Igni Con	1 tion trol+	ع Fuel L	5 .eak A	ecu P	6 Power+	ECU F	7 Power+	ہ CA	3 NH
	e Bac) kup	1 Pov	0 ver+	1 Sta	1 art+	1 Bac	2 kup	1 Bac	3 kup	1 Bac	4 kup	1 Bac	5 kup	
1 Pov	6 ver-	1 Pov	7 ver-	1 Charg	8 jer D+	1 Bac	9 kup	2 Fuel L	0 .eak B	2 Bac	1 kup	2 Bac	2 kup	2 CA	3 NL

Fig.13 Control Interface

ANOTE: This control interface is used for connecting Yuchai engine. If it can't meet demand, please contact manufacturer to re-customize the interface.

Table 22 Control Interface Terminal Definition

Pin	Definition	Size	Description
1	Backup		Backup interface, no wiring.
2	Power +	1.5mm ²	DC power positive input.
3	Start Output	1.5mm ²	Output when engine starts, 16A DC24V supply output
4	Ignition Control	1.5mm ²	Connect ignition switch of engine ECU, 16A DC24V supply output.
5	Fuel Leak A	0.5mm ²	Alarm input of fuel leak switch.
6	ECU Power+	1.5mm ²	FOLL nower oursely 16A DO24V oursely outsut
7	ECU Power+	1.5mm ²	ECO power supply, TBA DC24V supply output.
8	CANH	0.5mm ²	Monitoring controller connects engine CANBUS interface via it.
9	Backup		Backup interface, no wiring.
10	Power+	1.5mm ²	DC power positive input.
11	Start Output	1.5mm ²	Output when engine starts, 16A DC24V supply output.
12	Backup		Backup interface, no wiring.
13	Backup		Backup interface, no wiring.
14	Backup		Backup interface, no wiring.
15	Backup		Backup interface, no wiring.
16	Power-	1.5mm ²	DC power negative input.
17	Power-	1.5mm ²	DC power negative input.
18	Charger D+	0.5mm ²	Charger D+ interface, which can excite for charging generator and conduct charging failure voltage detection in starting.
19	Backup		Backup interface, no wiring.
20	Fuel Leak B	0.5mm ²	Negative input of fuel leak.
21	Backup		Backup interface, no wiring.
22	Backup		Backup interface, no wiring.
23	CANL	0.5mm ²	Monitoring controller connects engine CANBUS interface via it.
	TE: Power input, start out TE: 120Ω has been conne	put, ECU power	r output all need two wires to ensure max. 16A current outputting. NBUS interface that connecting ECU of monitoring controller internally.

11.7 MEM40 POWER SWITCH

is controller power switch, turn the switch to "On" position when it is working, while "Off" position when it is not working.

11.8 USB COMMUNICATION INTERFACE

This interface is designed for USB communication, which is Type-C with dust plug. When using, please pull it, connect USB data line, then connect PC can configure parameter and monitor data.

11.9 MEM40RM REAR PANEL



Fig.14 Remote Monitoring Module Rear Panel

Table 23 Remote Monitoring Interface Definition

Pin	Definition	Size	Description
1	Power+	mm ²	Power B+.
2	Power-	mm ²	Power B
3	NC		NC.
4	Emergency Stop	0.5mm ²	Emergency stop input.
5	CANL	0.5mm ²	It is used for connecting local monitoring controller, 120Ω
6	CANH	0.5mm ²	has been internally installed between CANH and CANL.

12 COMMISSIONING

It is suggested to do the following examination before formal system operation:

- Check all the connections are correct and wire diameter is suitable;
- Controller's positive and negative are correctly connected to starting battery and power switch is closed;
- Set controller in local mode. Press "Start", engine will start, it will automatically enter ETS after starting failure;
- Connect ignition control of controller to ECU power interface and engine ECU correctly;
- Test wire of remote monitoring module. In remote mode, press "Start" key of remote monitoring module, engine will start;
- If there is any other question, please contact SmartGen's service.

13 INSTALLATION

13.1 MEM40 DIMENSION AND INSTALLATION DIAGRAM

The monitoring controller comes with 4 shock absorbers with screw holes. 4 M8 screws (come with or add flat and spring washers) are required to be tightened from the mounting plate.



13.2 MEM40RM DIMENSION AND INSTALLATION DIAGRAM



Fig.16 MEM40RM Dimension and Installation Diagram

Mounting cautions:

4 M4 screws (flat and spring washers are required) and nuts for each are tightened from mounting plate in accordance with corresponding position. Select screws of appropriate length according to the thickness of the mounting plate.

13.3 BATTERY VOLTAGE INPUT

MEM40 monitoring controller can suit for battery voltage (8~35) VDC. The battery negative and positive wire connecting controller power B+/B- must be over 2.5mm². If floating charger is configured, please firstly connect output wires of charger to battery's positive and negative directly, and then connect wires from battery's positive and negative to controller's positive and negative input ports separately in order to prevent the charger from disturbing the controller's normal working.

13.4 RPU SPEED SENSOR INPUT

RPU speed sensor is the magnetic equipment installed on the engine to detect flywheel teeth number. The wires used to connect with the controller shall be 2-core shielding wires. The shielding layer shall be single-grounded, and the other two signal wires shall be connected to No.6 and No.7 terminals of RPU interface. The output voltage of the speed sensor shall be within (1~24) VAC (effective value) in the range of full speed and 12VAC is recommended (at rated speed). As to RPU

speed sensor installation, the sensor can be firstly spun to the connection flywheel, then invert 1/3 lap, and finally tighten up the nut on the sensor.

13.5 SENSOR INPUT

Aux. sensor 1,2,3 of MEM40 monitoring controller can be configured as current/voltage/resistance type sensor, please select corresponding sensor input signal according to engine sensor type.

14 TROUBLESHOOTING

Problem	Possible Solution					
Controllor no rosponso	Check starting batteries;					
with nowor	Check controller wirings;					
with power	Check DC fuse.					
Controller emergency	Check if emergency stop button function is correct.					
stop						
Sensor open alarm	Check if sensor and its wirings are correct;					
	Check if the configured sensor type is correct.					
Alarm shutdown in	Check related switches and wirings according to LCD information;					
running	Check Aux. input ports.					
	Check fuel circuit and its wirings;					
Cronk failura	Check starting batteries;					
	Check speed sensor and its wirings;					
	Check engine manual.					
Ctartar na raananaa	Check starter wirings;					
Starter no response	Check starting batteries.					
	Check wirings;					
RS485 communication	Check if RS485's A and B wires are connected in the opposite way;					
failure	Check if PC's communication port is damaged;					
	Putting a 120Ω resistor between RS485's A and B is recommended.					
CANBUS	Check wirings;					
communication failure	Check if CANBUS CANH and CANL wires are connected in the opposite way.					

Table 38 Troubleshooting